

# System SLIO

FM | 050-1BB00 | Manual

HB300 | FM | 050-1BB00 | en | 24-30

Counter module 2x32Bit - FM 050



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# 1 General

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## 1.2 About this manual

### Objective and contents

This manual describes the FM 050-1BB00 of the System SLIO.

- It describes the structure, configuration and application.
- The manual is targeted at users who have a background in automation technology.
- The manual consists of chapters. Each chapter describes a completed topic.
- For guidance, the manual provides:
  - An overall table of contents at the beginning of the manual.
  - References with pages numbers.

### Validity of the documentation

Product	Order no.	as of state:
FM 050	050-1BB00	HW: 01

### Icons and headings

Important passages in the text are highlighted by following icons and headings:



#### **DANGER**

Immediate or likely danger. Personal injury is possible.



#### **CAUTION**

Damages to property is likely if these warnings are not heeded.



*Supplementary information and useful tips.*

## 1.3 Safety instructions

### Suitability for use

- It is the customer's responsibility to confirm conformity with any standards, codes, or regulations that apply if the Yaskawa product is used in combination with any other products.
- The customer must confirm that the Yaskawa product is suitable for the systems, machines, and equipment used by the customer.
- If the Yaskawa product is used in a manner not specified in the manual, the protection provided by the Yaskawa product may be impaired.
- Consult with Yaskawa to determine whether use in the following applications is acceptable. If use in the application is acceptable, use the Yaskawa product with extra allowance in ratings and specifications, and provide safety measures to minimize hazards in the event of failure.
  - Outdoor use, use involving potential chemical contamination or electrical interference, or use in conditions or environments not described in product catalogs or manuals
  - Nuclear energy control systems, combustion systems, railroad systems, aviation systems, vehicle systems, medical equipment, amusement machines, and installations subject to separate industry or government regulations
  - Systems, machines, and equipment that may present a risk to life or property
  - Systems that require a high degree of reliability, such as systems that supply gas, water, or electricity, or systems that operate continuously 24 hours a day
  - Other systems that require a similar high degree of safety
- Never use the Yaskawa product for an application involving serious risk to life or property without first ensuring that the system is designed to secure the required level of safety with risk warnings and redundancy, and that the Yaskawa product is properly rated and installed.
- The circuit examples and other application examples described in product catalogs and manuals are for reference. Check the functionality and safety of the actual devices and equipment to be used before using the Yaskawa product.
- Read and understand all use prohibitions and precautions, and operate the Yaskawa product correctly to prevent accidental harm to third parties.

### Field of application

The system is constructed and produced for:

- communication and process control
- general control and automation tasks
- industrial applications
- operation within the environmental conditions specified in the technical data
- installation into a cubicle



#### **DANGER**

This device is not certified for applications in

- in explosive environments (EX-zone)

**Exclusion of Liability**

- The Yaskawa product is not suited for use in life-support machines or systems.
- Contact a Yaskawa representative or your Yaskawa sales representative if you are considering the application of this Yaskawa product for special purposes, such as machines or systems used for passenger cars, medicine, airplanes and aerospace, nuclear power, electric power or undersea relaying.

**DANGER**

When you use this Yaskawa product in applications where its failure could cause the loss of human life, a serious accident, or physical injury, you must install applicable safety devices.

- If you do not correctly install safety devices, it can cause serious injury or death.

**Disposal**

National rules and regulations apply to the disposal of the unit!

**Documentation**

The manual must be available to all personnel in the:

- project design department
- installation department
- commissioning
- operation

**CAUTION**

The following conditions must be met before using or commissioning the components described in this manual:

- Hardware modifications to the process control system should only be carried out when the system has been disconnected from power!
- Installation and hardware modifications only by properly trained personnel.
- The national rules and regulations of the respective country must be satisfied (installation, safety, EMC ...)

## 2 Basics and mounting

### 2.1 Safety notes for the user



#### DANGER

##### Protection against dangerous voltages

- When using System SLIO modules, the user must be protected from touching hazardous voltage.
- You must therefore create an insulation concept for your system that includes safe separation of the potential areas of ELV and hazardous voltage.
- Here, observe the insulation voltages between the potential areas specified for the System SLIO modules and take suitable measures, such as using PELV/SELV power supplies for System SLIO modules.

#### Handling of electrostatic sensitive modules

The modules are equipped with highly integrated components in MOS technology. These components are highly sensitive to over-voltages that occur, e.g. with electrostatic discharge. The following symbol is used to identify these hazardous modules:



The symbol is located on modules, module racks or on packaging and thus indicates electrostatic sensitive modules. Electrostatic sensitive modules can be destroyed by energies and voltages that are far below the limits of human perception. If a person who is not electrically discharged handles electrostatic sensitive modules, voltages can occur and damage components and thus impair the functionality of the modules or render the modules unusable. Modules damaged in this way are in most cases not immediately recognized as faulty. The error can only appear after a long period of operation. Components damaged by static discharge can show temporary faults when exposed to temperature changes, vibrations or load changes. Only the consistent use of protective devices and responsible observance of the handling rules can effectively prevent malfunctions and failures on electrostatic sensitive modules.

#### Shipping of modules

Please always use the original packaging for shipping.

#### Measurement and modification of electrostatic sensitive modules

For measurements on electrostatic sensitive modules the following must be observed:

- Floating measuring instruments must be discharged before use.
- Measuring instruments used must be grounded.

When modifying electrostatic sensitive modules, ensure that a grounded soldering iron is used.



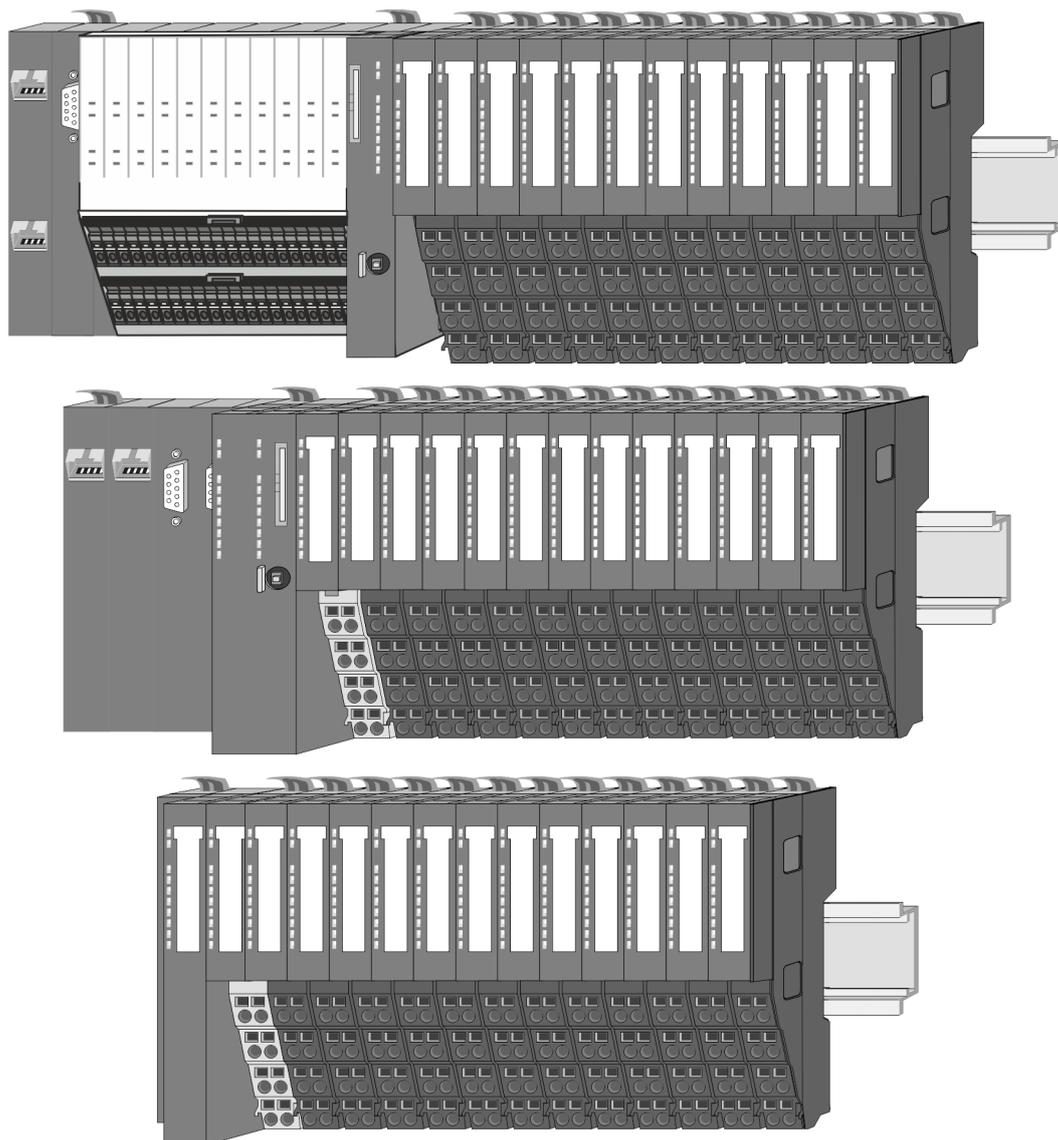
#### CAUTION

When working with and on electrostatic sensitive modules, make sure that personnel and equipment are adequately grounded.

## 2.2 System conception

### 2.2.1 Overview

The System SLIO is a modular automation system for assembly on a 35mm mounting rail. By means of the periphery modules with 2, 4, 8 and 16 channels this system may properly be adapted matching to your automation tasks. The wiring complexity is low, because the supply of the DC 24V power section supply is integrated to the backplane bus and defective modules may be replaced with standing wiring. By deployment of the power modules in contrasting colors within the system, further isolated areas may be defined for the DC 24V power section supply, respectively the electronic power supply may be extended with 2A.



## 2.2.2 Components

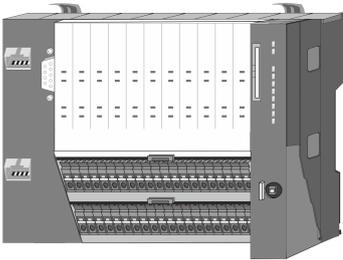
- CPU (head module)
- Bus coupler (head module)
- Line extension
- 8x periphery modules
- 16x periphery modules
- Power modules
- Accessories



**CAUTION**

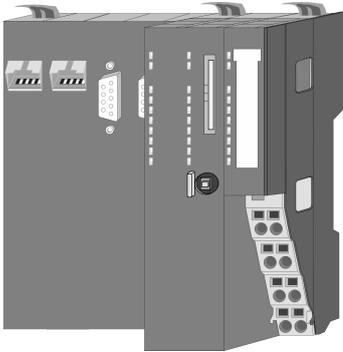
Only Yaskawa modules may be combined. A mixed operation with third-party modules is not allowed!

### CPU 01xC



With the CPU 01xC electronic, input/output components and power supply are integrated to one casing. In addition, up to 64 periphery modules of the System SLIO can be connected to the backplane bus. As head module via the integrated power module for power supply CPU electronic and the I/O components are supplied as well as the electronic of the periphery modules, which are connected via backplane bus. To connect the power supply of the I/O components and for DC 24V power section supply of via backplane bus connected periphery modules, the CPU has removable connectors. By installing of up to 64 periphery modules at the backplane bus, these are electrically connected, this means these are assigned to the backplane bus, the electronic modules are power supplied and each periphery module is connected to the DC 24V power section supply.

### CPU 01x



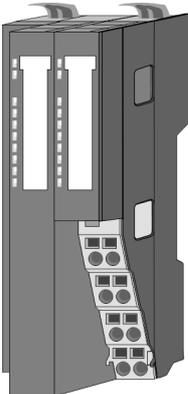
With this CPU 01x, CPU electronic and power supply are integrated to one casing. As head module, via the integrated power module for power supply, CPU electronic and the electronic of the connected periphery modules are supplied. The DC 24V power section supply for the linked periphery modules is established via a further connection of the power module. By installing of up to 64 periphery modules at the backplane bus, these are electrically connected, this means these are assigned to the backplane bus, the electronic modules are power supplied and each periphery module is connected to the DC 24V power section supply.



**CAUTION**

CPU part and power module may not be separated!  
Here you may only exchange the electronic module!

### Bus coupler



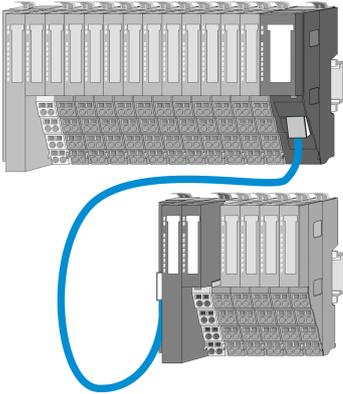
With a bus coupler bus interface and power module is integrated to one casing. With the bus interface you get access to a subordinated bus system. As head module, via the integrated power module for power supply, bus interface and the electronic of the connected periphery modules are supplied. The DC 24V power section supply for the linked periphery modules is established via a further connection of the power module. By installing of up to 64 periphery modules at the bus coupler, these are electrically connected, this means these are assigned to the backplane bus, the electronic modules are power supplied and each periphery module is connected to the DC 24V power section supply.



**CAUTION**

Bus interface and power module may not be separated!  
Here you may only exchange the electronic module!

**Line extension**

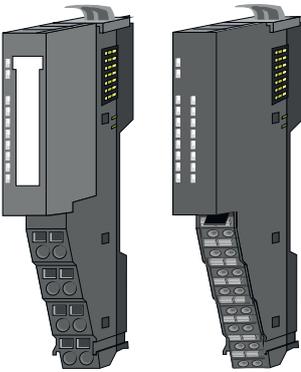


In the System SLIO there is the possibility to place up to 64 modules in on line. By means of the line extension you can divide this line into several lines. Here you have to place a line extension master at each end of a line and the subsequent line has to start with a line extension slave. Master and slave are to be connected via a special connecting cable. In this way, you can divide a line on up to 5 lines. Depending on the line extension, the max. number of pluggable modules at the System SLIO bus is decreased accordingly. To use the line extension no special configuration is required.



*Please note that some modules do not support line extensions due to the system. For more information, please refer to the compatibility list. This can be found in the 'Download Center' of [www.yaskawa.eu.com](http://www.yaskawa.eu.com) under 'System SLIO Compatibility list'.*

**Periphery modules**

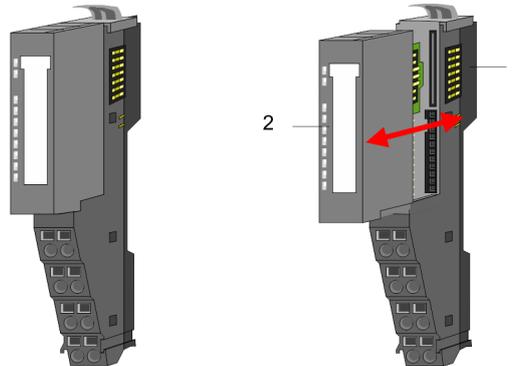


The periphery modules are available in the following 2 versions, whereby of each the electronic part can be replaced with standing wiring:

- 8x periphery module for a maximum of 8 channels.
- 16x periphery module for a maximum of 16 channels.

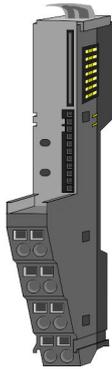
**8x periphery modules**

Each 8x periphery module consists of a *terminal* and an *electronic module*.



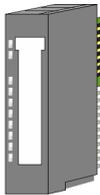
- 1 Terminal module
- 2 Electronic module

**Terminal module**



The *terminal module* serves to carry the electronic module, contains the backplane bus with power supply for the electronic, the DC 24V power section supply and the staircase-shaped terminal for wiring. Additionally the terminal module has a locking system for fixing at a mounting rail. By means of this locking system your system may be assembled outside of your switchgear cabinet to be later mounted there as whole system.

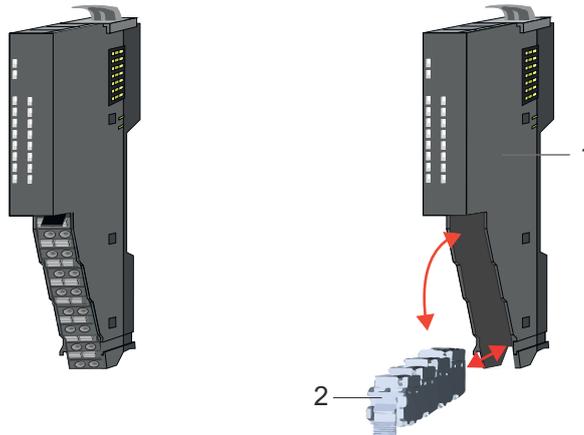
**Electronic module**



The functionality of a periphery module is defined by the *electronic module*, which is mounted to the terminal module by a sliding mechanism. With an error the defective electronic module may be exchanged for a functional module with standing installation. At the front side there are LEDs for status indication. For simple wiring each module shows corresponding connection information at the front and at the side.

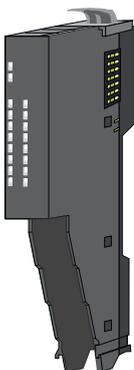
**16x periphery modules**

Each 16x periphery module consists of an *electronic unit* and a *terminal block*.



- 1 Electronic unit
- 2 Terminal block

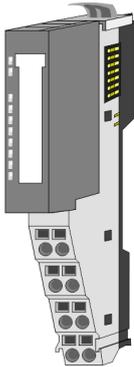
**Electronic unit**



With the 16x periphery module the terminal block is connected to the *electronic unit* via a secure flap mechanism. In the case of an error you can exchange the defective electronic unit for a functional unit with standing wiring. At the front side there are LEDs for status indication. For easy wiring each electronic unit shows corresponding connection information at the side. The electronic unit provides the slot for the terminal block for the wiring and contains the backplane bus with power supply for the electronic and the connection to the DC 24V power section supply. Additionally the electronic unit has a locking system for fixing it at a mounting rail. By means of this locking system your system may be assembled outside of your switchgear cabinet to be later mounted there as whole system.

**Terminal block**

The *terminal block* provides the electrical interface for the signalling and supplies lines of the module. When mounting the terminal block, it is attached to the bottom of the electronic unit and turned towards the electronic unit until it clicks into place. With the wiring a "push-in" spring-clip technique is used. This allows a quick and easy connection of your signal and supply lines. The clamping off takes place by means of a screwdriver.

**Power module**

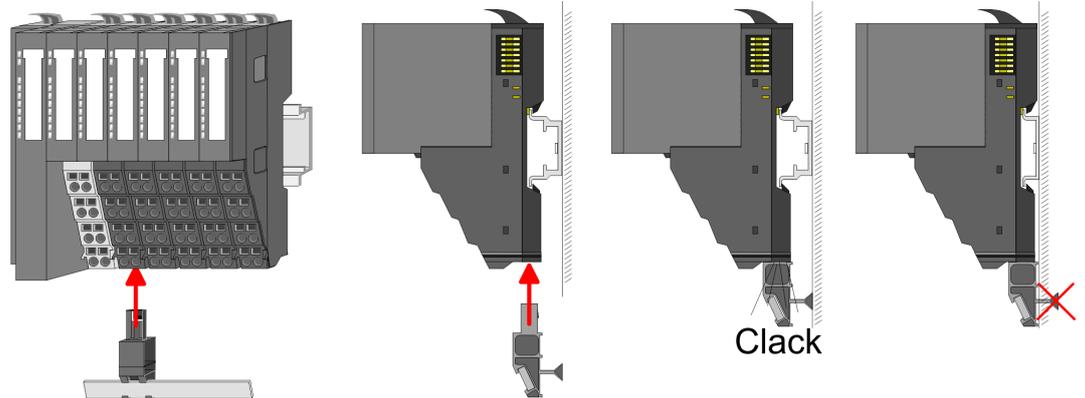
In the System SLIO the power supply is established by power modules. These are either integrated to the head module or may be installed between the periphery modules. Depending on the power module isolated areas of the DC 24V power section supply may be defined respectively the electronic power supply may be extended with 2A. For better recognition the colour of the power modules are contrasting to the periphery modules.

**2.2.3 Accessories****Shield bus carrier**

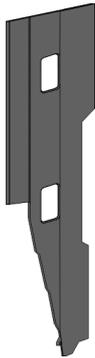
*Please note that a shield bus carrier cannot be mounted on a 16x periphery module!*



The shield bus carrier (order no.: 000-0AB00) serves to carry the shield bus (10mm x 3mm) to connect cable shields. Shield bus carriers, shield bus and shield fixings are not in the scope of delivery. They are only available as accessories. The shield bus carrier is mounted underneath the terminal of the terminal module. With a flat mounting rail for adaptation to a flat mounting rail you may remove the spacer of the shield bus carrier.



**Bus cover**



With each head module, to protect the backplane bus connectors, there is a mounted bus cover in the scope of delivery. You have to remove the bus cover of the head module before mounting a System SLIO module. For the protection of the backplane bus connector you always have to mount the bus cover at the last module of your system again. The bus cover has the order no. 000-0AA00.

**Coding pins**



*Please note that a coding pin cannot be installed on a 16x periphery module! Here you have to make sure that the associated terminal block is plugged again when the electronics unit is replaced.*

There is the possibility to fix the assignment of electronic and terminal module. Here coding pins (order number 000-0AC00) can be used. The coding pin consists of a coding jack and a coding plug. By combining electronic and terminal module with coding pin, the coding jack remains in the electronic module and the coding plug in the terminal module. This ensures that after replacing the electronic module just another electronic module can be plugged with the same encoding.

**Spare parts**

The following spare parts are available for the System SLIO:

Spare part	Order no.	Description	Packaging unit
	092-9BH00	Terminal block for System SLIO 16x periphery module.	5 pieces
	092-9BK00	Connector for System SLIO CPU 013C.	5 pieces



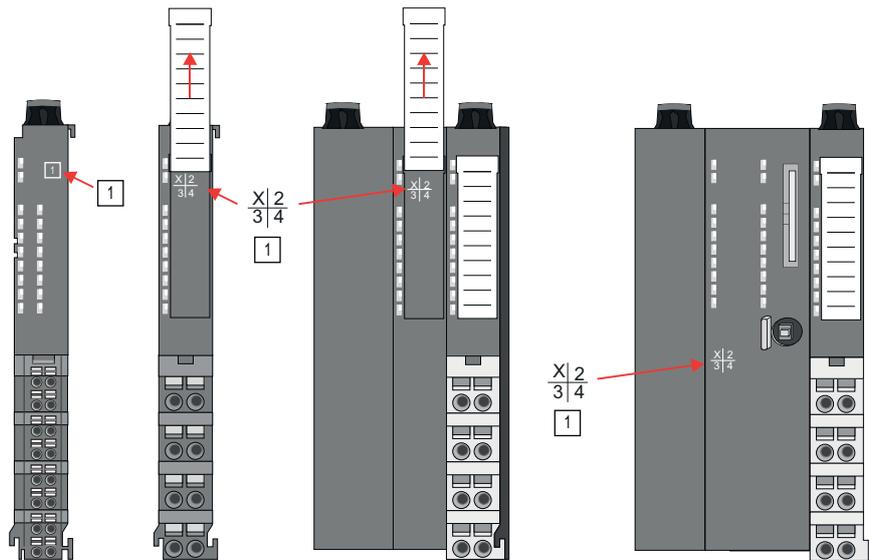
**CAUTION**

Please note that you may only use the spare parts with Yaskawa modules. Use with third-party modules is not allowed!

### 2.2.4 Hardware revision

#### Hardware revision on the front

- The hardware revision is printed on every System SLIO module.
- Since a System SLIO 8x peripheral module consists of a terminal and electronic module, you will find a hardware revision printed on each of them.
- Authoritative for the hardware revision of a System SLIO module is the hardware revision of the electronic module. This is located under the labeling strip of the corresponding electronic module.
- Depending on the module type, there are the following 2 variants e.g. to indicate hardware revision 1:
  - With current labelling there is a 1 on the front.
  - With earlier labelling, the 1 is marked with 'X' on a number grid.



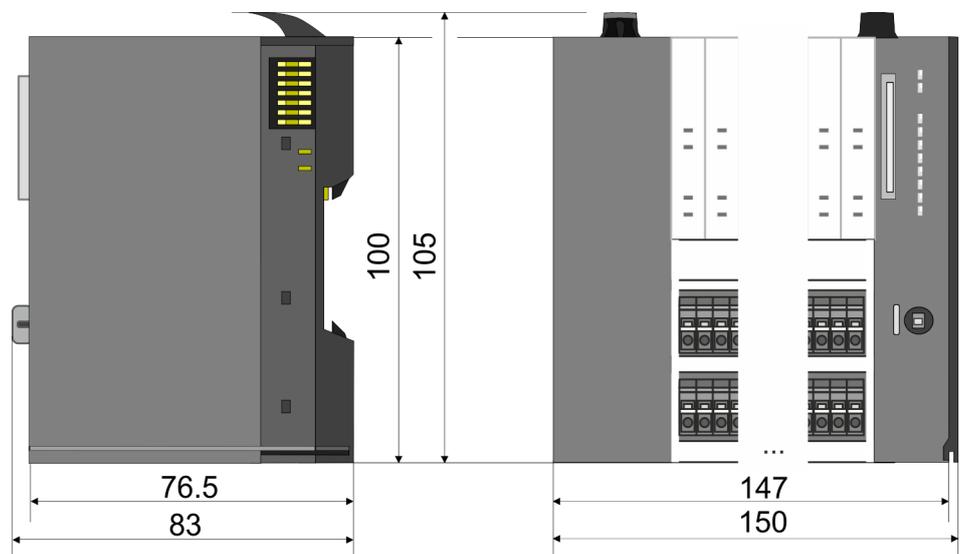
#### Hardware revision via web server

On the CPUs and some bus couplers, you can check the hardware revision 'HW Revision' via the integrated web server.

## 2.3 Dimensions

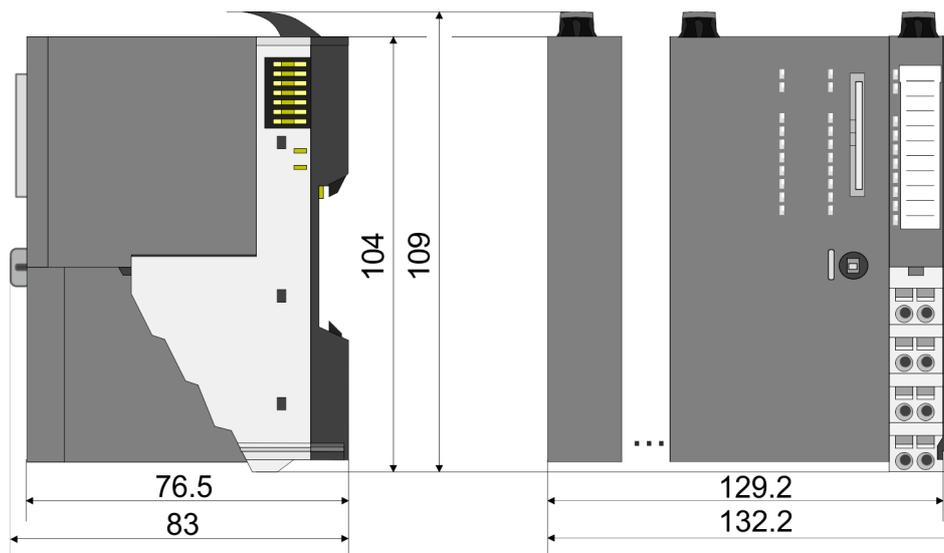
### CPU 01xC

All dimensions are in mm.

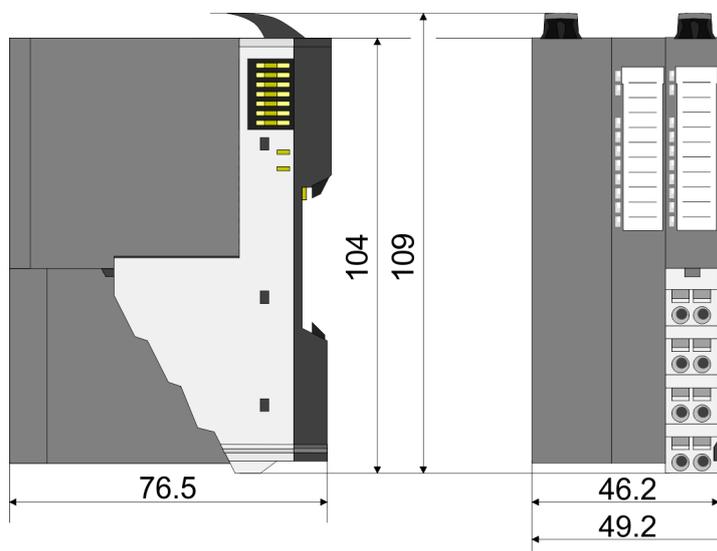


Dimensions

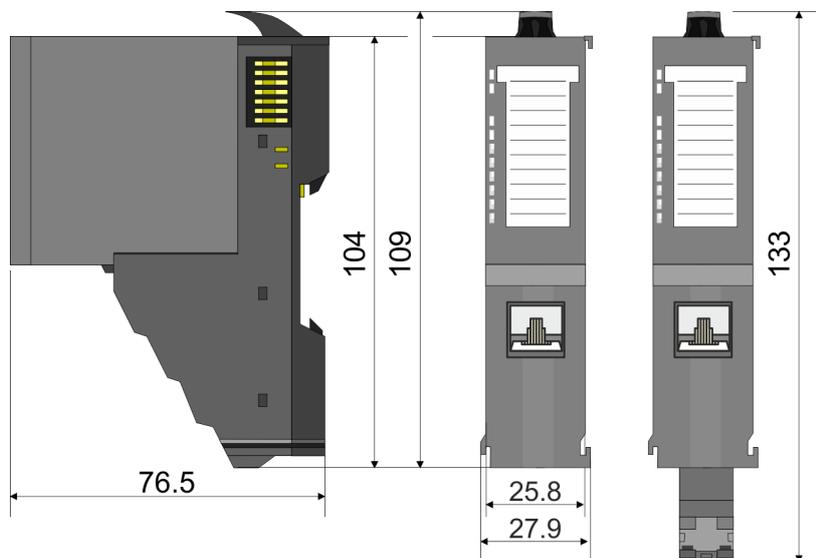
CPU 01x



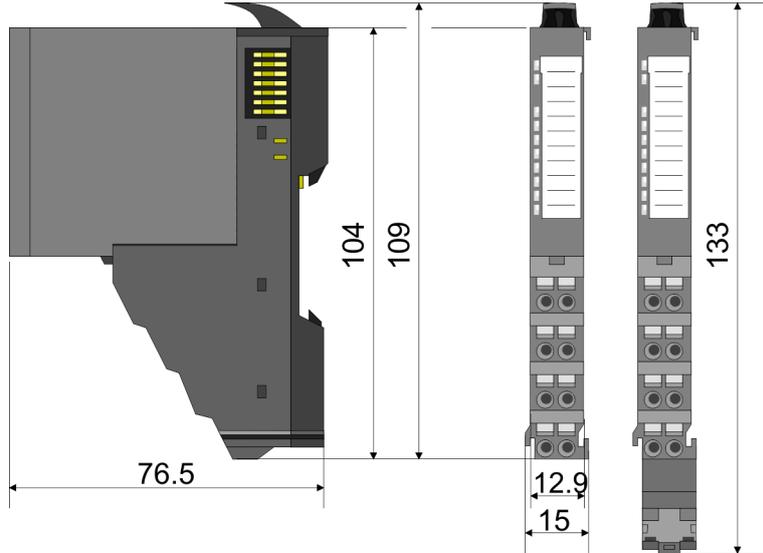
Bus coupler and line extension slave



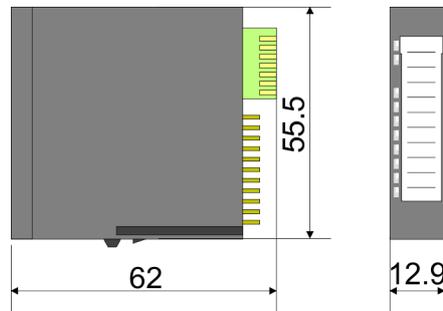
Line extension master



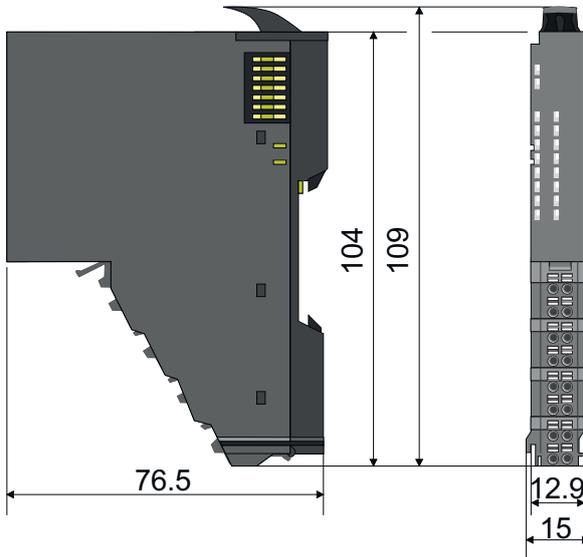
8x periphery module



Electronic module



16x periphery module



## 2.4 Mounting 8x periphery modules



**CAUTION**

**Requirements for UL compliance use**

- Use for power supply exclusively SELV/PELV power supplies.
- The System SLIO must be installed and operated in a housing according to IEC 61010-1 9.3.2 c).

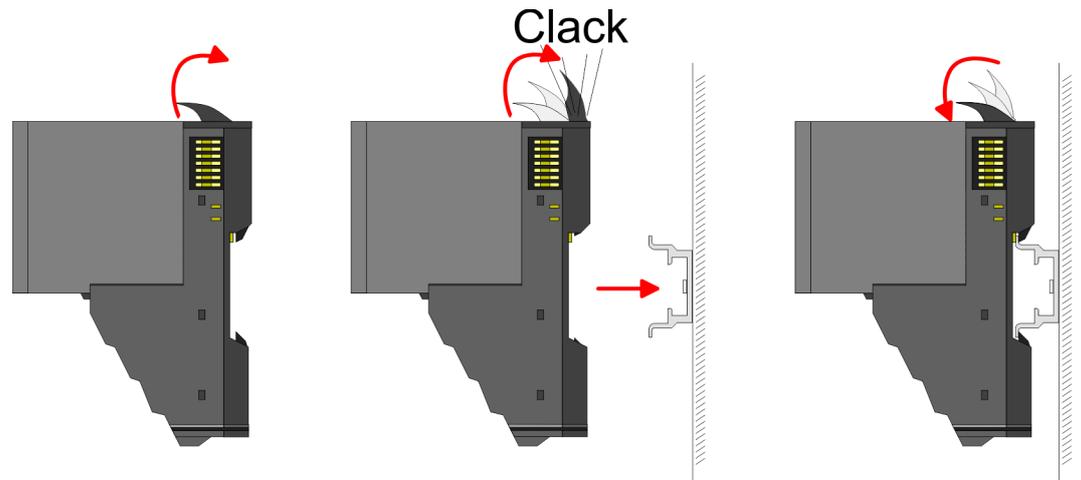


**CAUTION**

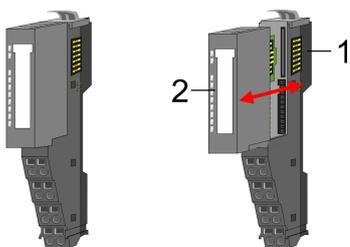
**Danger of injury from electrical shock and damage to the unit!**

Put the System SLIO in a safe, powered down state before starting installation, disassembly or wiring of the System SLIO modules!

There is a locking lever at the top side of the module. For mounting and demounting this locking lever is to be turned upwards until this engages. For mounting place the module to the module installed before and push the module to the mounting rail guided by the strips at the upper and lower side of the module. The module is fixed to the mounting rail by pushing downward the locking lever. The modules may either separately be mounted to the mounting rail or as block. Here is to be considered that each locking lever is opened. The modules are each installed on a mounting rail. The electronic and power section supply are connected via the backplane bus. Up to 64 modules may be mounted. Please consider here that the sum current of the electronic power supply does not exceed the maximum value of 3A. By means of the power module 007-1AB10 the current of the electronic power supply may be expanded accordingly.



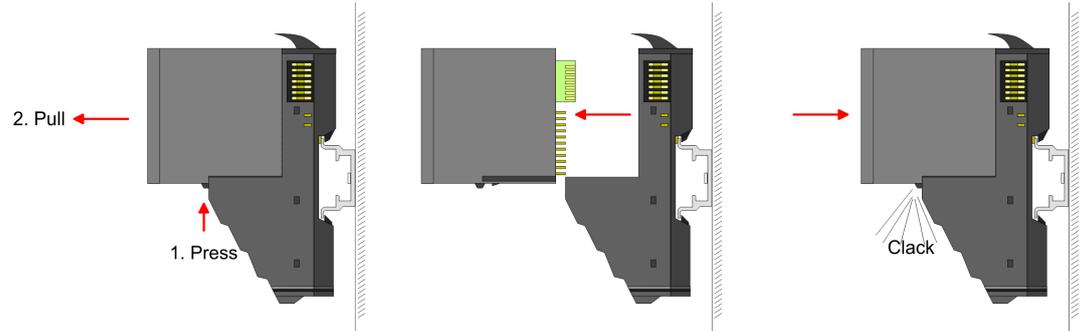
**Terminal and electronic module**



Each periphery module consists of a *terminal* and an *electronic module*.

- 1 Terminal module
- 2 Electronic module

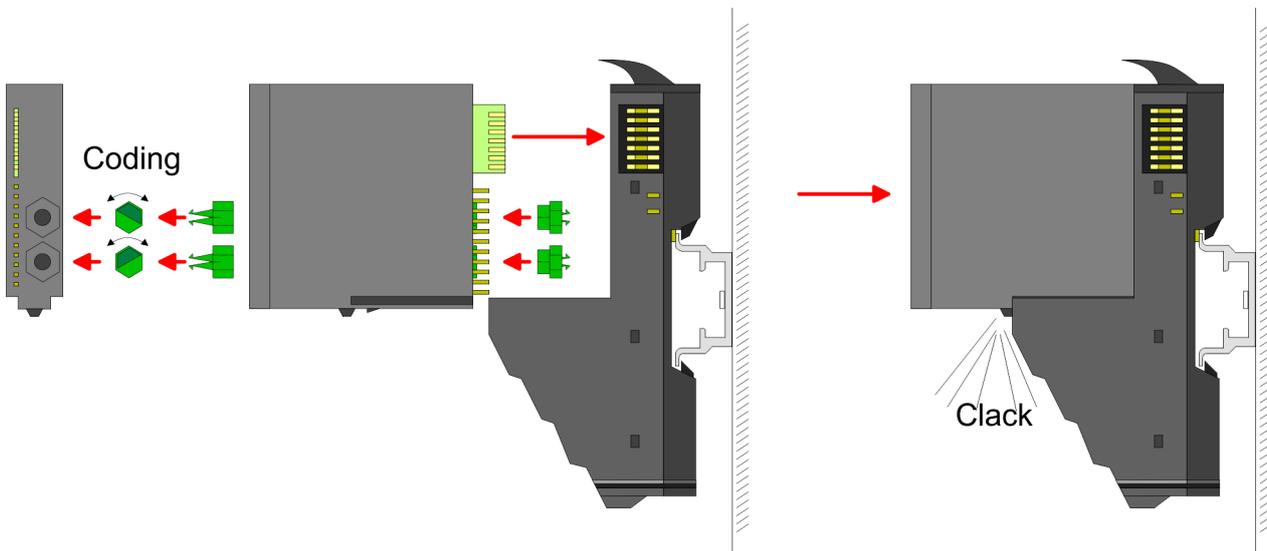
For the exchange of a electronic module, the electronic module may be pulled forward after pressing the unlocking lever at the lower side of the module. For installation plug the electronic module guided by the strips at the lower side until this engages audible to the terminal module.



### Coding



There is the possibility to fix the assignment of electronic and terminal module. Here coding pins (order number 000-0AC00) can be used. The coding pin consists of a coding jack and a coding plug. By combining electronic and terminal module with coding pin, the coding jack remains in the electronic module and the coding plug in the terminal module. This ensures that after replacing the electronics module just another electronic module can be plugged with the same encoding.



Each electronic module has on its back 2 coding sockets for coding jacks. Due to the characteristics, with the coding jack 6 different positions can be plugged, each. Thus there are 36 possible combinations for coding with the use of both coding sockets.

1. Plug, according to your coding, 2 coding jacks in the coding sockets of your electronic module until they lock
2. Now plug the according coding plugs into the coding jacks.
3. To fix the coding put both the electronic and terminal module together until they lock



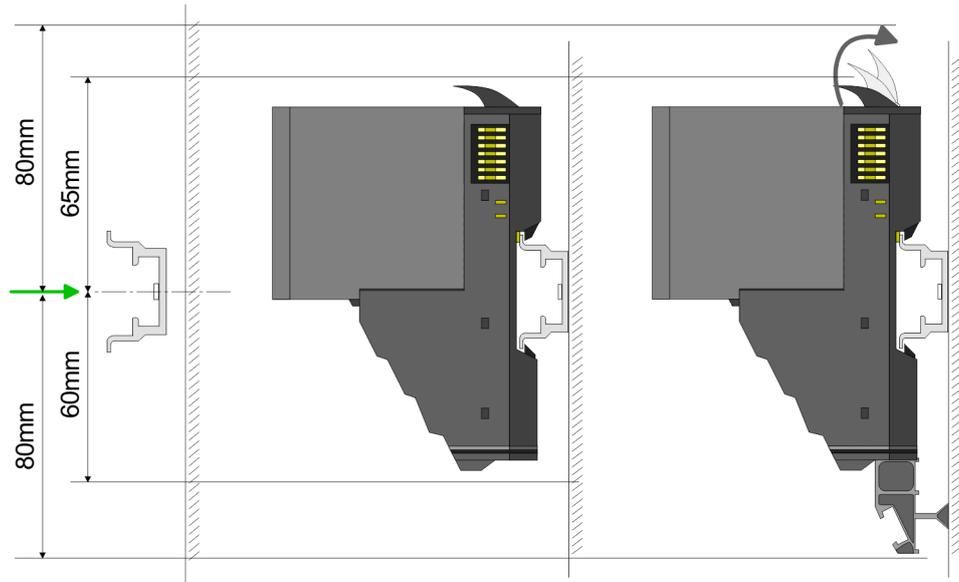
#### CAUTION

Please consider that when replacing an already coded electronic module, this is always be replaced by an electronic module with the same coding.

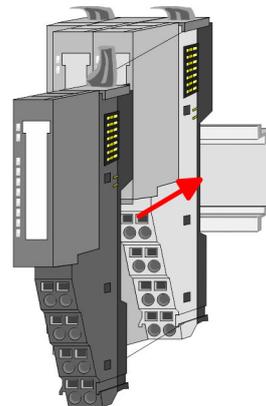
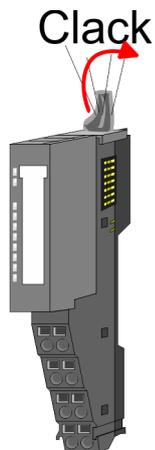
Even with an existing coding on the terminal module, you can plug an electronic module without coding. The user is responsible for the correct usage of the coding pins. Yaskawa assumes no liability for incorrectly attached electronic modules or for damages which arise due to incorrect coding!

Mounting 8x periphery modules

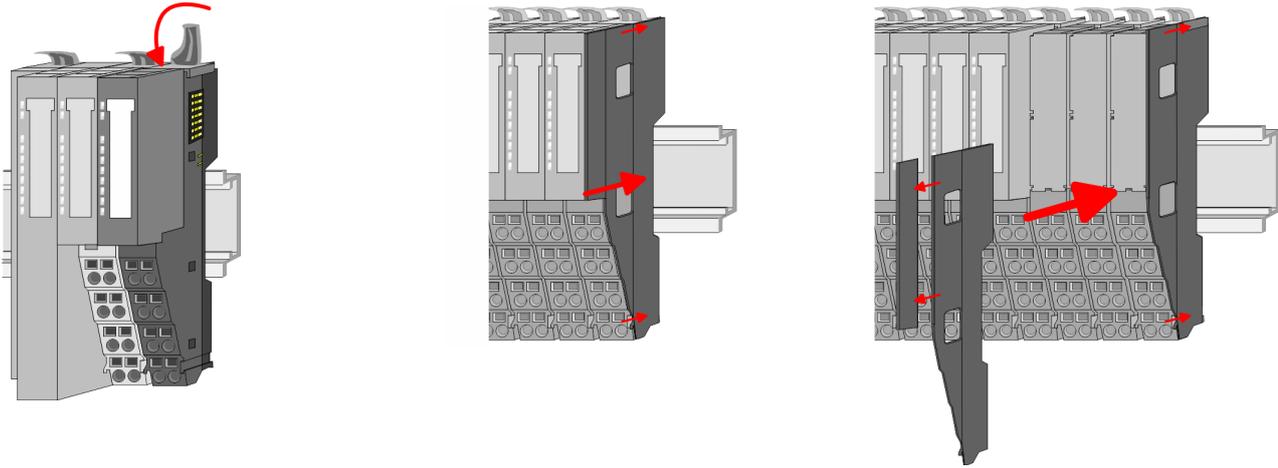
Mounting periphery modules



1. ➤ Mount the mounting rail! Please consider that a clearance from the middle of the mounting rail of at least 80mm above and 60mm below, respectively 80mm by deployment of shield bus carriers, exist.
2. ➤ Mount your head module such as CPU or field bus coupler.
3. ➤ Before mounting the periphery modules you have to remove the bus cover at the right side of the head module by pulling it forward. Keep the cover for later mounting.



4. ➤ For mounting turn the locking lever of the module upwards until it engages.
5. ➤ For mounting place the module to the module installed before and push the module to the mounting rail guided by the strips at the upper and lower side of the module.
6. ➤ Turn the locking lever of the periphery module downward, again.



7. After mounting the whole system, to protect the backplane bus connectors at the last module you have to mount the bus cover, now. If the last module is a clamp module, for adaptation the upper part of the bus cover is to be removed.

## 2.5 Mounting 16x periphery modules



### CAUTION

#### Requirements for UL compliance use

- Use for power supply exclusively SELV/PELV power supplies.
- The System SLIO must be installed and operated in a housing according to IEC 61010-1 9.3.2 c).



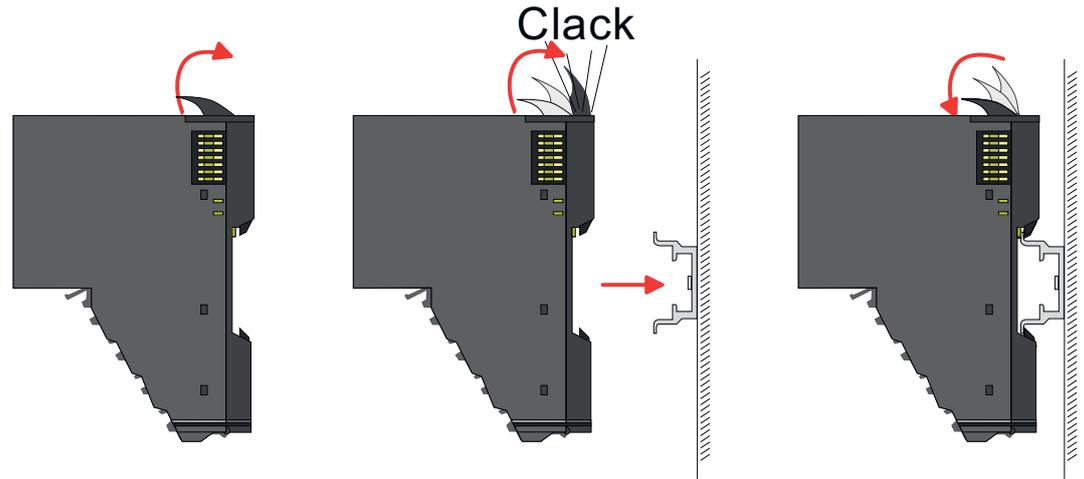
### CAUTION

#### Danger of injury from electrical shock and damage to the unit!

Put the System SLIO in a safe, powered down state before starting installation, disassembly or wiring of the System SLIO modules!

There is a locking lever at the top side of the module. For mounting and demounting this locking lever is to be turned upwards until this engages. For mounting place the module to the module installed before and push the module to the mounting rail guided by the strips at the upper and lower side of the module. The module is fixed to the mounting rail by pushing downward the locking lever. The modules may either separately be mounted to the mounting rail or as block. Here is to be considered that each locking lever is opened. The modules are each installed on a mounting rail. The electronic and power section supply are connected via the backplane bus. Up to 64 modules may be mounted. Please consider here that the sum current of the electronic power supply does not exceed the maximum value of 3A. By means of the power module 007-1AB10 the current of the electronic power supply may be expanded accordingly.

Mounting 16x periphery modules

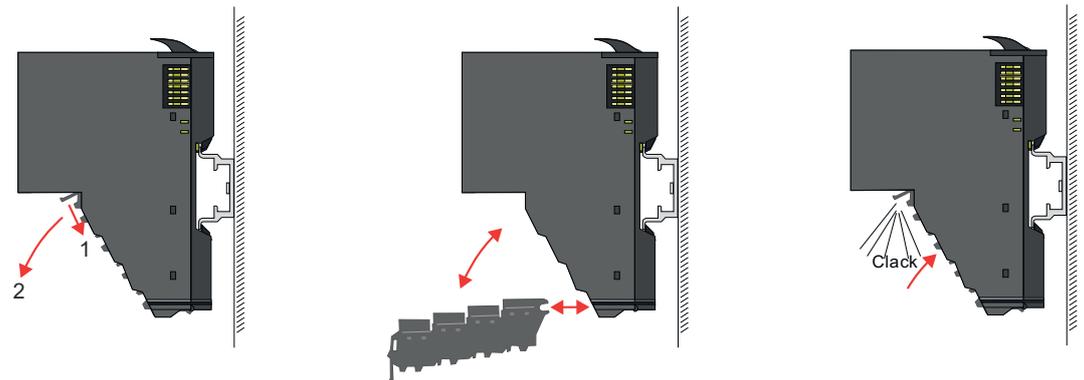
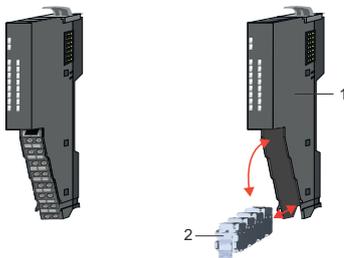


Electronic unit and terminal block

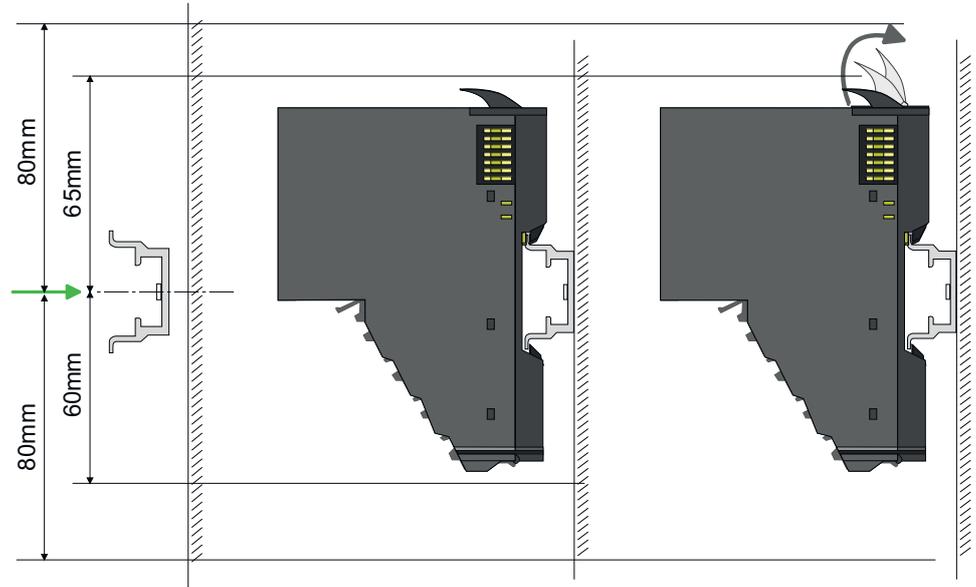
Each 16x periphery module consists of an *electronic unit* and a *terminal block*.

- 1 Electronic unit
- 2 Terminal block

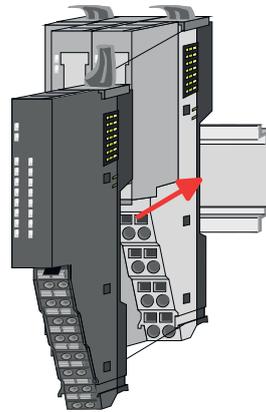
To replace an electronic unit, you can push down and pull off the terminal block after releasing the lock. To mount the terminal block, place it horizontally on the lower side of the electronic unit and push it towards the electronic unit until it clicks into place.



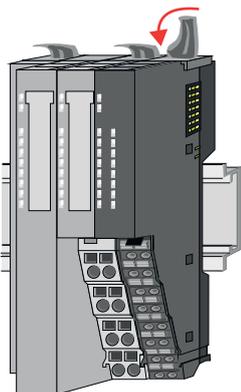
Mounting periphery module

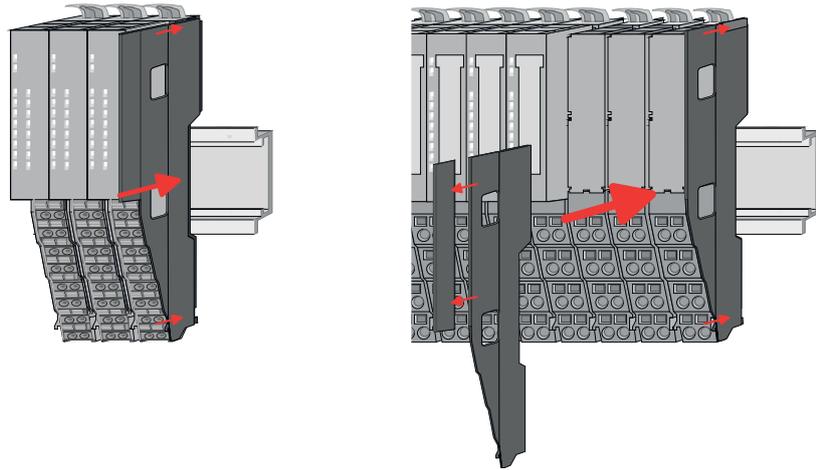


1. ➤ Mount the mounting rail! Please consider that a clearance from the middle of the mounting rail of at least 80mm above and 80mm below exist.
2. ➤ Mount your head module such as CPU or field bus coupler.
3. ➤ Before mounting the periphery modules you have to remove the bus cover at the right side of the head module by pulling it forward. Keep the cover for later mounting.



4. ➤ For mounting turn the locking lever of the module upwards until it engages.
5. ➤ For mounting place the module to the module installed before and push the module to the mounting rail guided by the strips at the upper and lower side of the module.
6. ➤ Turn the locking lever of the periphery module downward, again.





7. → After mounting the whole system, to protect the backplane bus connectors at the last module you have to mount the bus cover, now. If the last module is a clamp module, for adaptation the upper part of the bus cover is to be removed.

## 2.6 Wiring 8x periphery modules

### Terminal module terminals



**CAUTION**

**Do not connect hazardous voltages!**

If this is not explicitly stated in the corresponding module description, hazardous voltages are not allowed to be connected to the corresponding terminal module!



**CAUTION**

**Danger of injury from electrical shock and damage to the unit!**

Put the System SLIO in a safe, powered down state before starting installation, disassembly or wiring of the System SLIO modules!



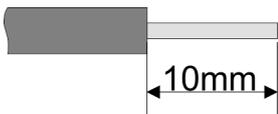
**CAUTION**

**Consider temperature for external cables!**

Cables may experience temperature increase due to system heat dissipation. Thus the cabling specification must be chosen 25°C above ambient temperature!

- With wiring the terminal modules, terminals with spring clamp technology are used for wiring. The spring clamp technology allows quick and easy connection of your signal and supply lines. In contrast to screw terminal connections this type of connection is vibration proof.

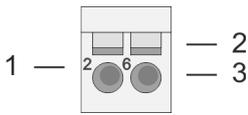
**Data**



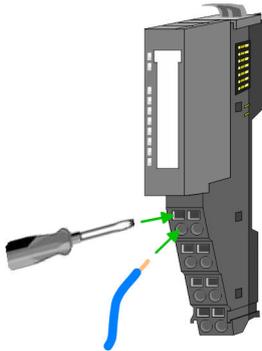
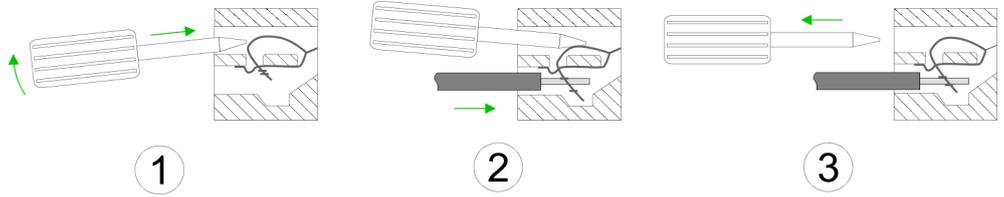
Please use copper wire only!

$U_{max}$	240V AC / 30V DC
$I_{max}$	10A
Cross section	0.08 ... 1.5mm <sup>2</sup> (AWG 28 ... 16)
Stripping length	10mm

## Wiring procedure



- 1 Pin number at the connector
- 2 Opening for screwdriver
- 3 Connection hole for wire



1. Insert a suited screwdriver at an angle into the square opening as shown. Press and hold the screwdriver in the opposite direction to open the contact spring.
2. Insert the stripped end of wire into the round opening. You can use wires with a cross section of 0.08mm<sup>2</sup> up to 1.5mm<sup>2</sup>
3. By removing the screwdriver, the wire is securely fixed via the spring contact to the terminal.

Shield attachment → [Chap. 2.9 'Shielding' ...page 30](#)

## 2.7 Wiring 16x periphery modules

## Terminal block connectors

**CAUTION****Do not connect hazardous voltages!**

If this is not explicitly stated in the corresponding module description, hazardous voltages are not allowed to be connected to the corresponding terminal block!

**CAUTION****Danger of injury from electrical shock and damage to the unit!**

Put the System SLIO in a safe, powered down state before starting installation, disassembly or wiring of the System SLIO modules!

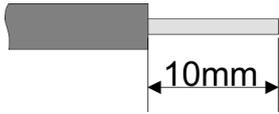
**CAUTION****Consider temperature for external cables!**

Cables may experience temperature increase due to system heat dissipation. Thus the cabling specification must be chosen 25°C above ambient temperature!

- The 16x periphery module has a removable terminal block for wiring.
- With the wiring of the terminal block a "push-in" spring-clip technique is used. This allows a quick and easy connection of your signal and supply lines.
- The clamping off takes place by means of a screwdriver.

Wiring power modules

Data



Please use copper wire only!

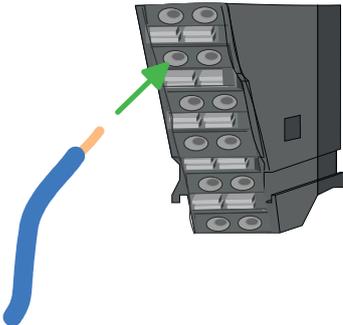
$U_{max}$	30V DC
$I_{max}$	10A
Cross section solid wire	0.25 ... 0.75mm <sup>2</sup>
Cross section with ferrule	0.14 ... 0.75mm <sup>2</sup>
AWG	24 ... 16
Stripping length	10mm

Wiring procedure



- 1 Release area
- 2 Connection hole for wire

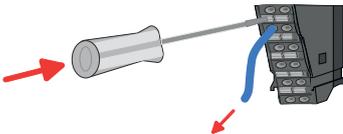
Insert wire



The wiring happens without a tool.

1. Determine according to the casing labelling the connection position.
2. Insert through the round connection hole of the according contact your prepared wire until it stops, so that it is fixed.
  - ➔ By pushing the contact spring opens, thus ensuring the necessary contact pressure.

Remove wire



The wire is to be removed by means of a screwdriver with 2.5mm blade width.

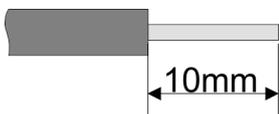
1. Press with your screwdriver vertically at the release button.
  - ➔ The contact spring releases the wire.
2. Pull the wire from the round hole.

## 2.8 Wiring power modules

Terminal module terminals

Power modules are either integrated to the head module or may be installed between the periphery modules. With power modules, terminals with spring clamp technology are used for wiring. The spring clamp technology allows quick and easy connection of your signal and supply lines. In contrast to screw terminal connections this type of connection is vibration proof.

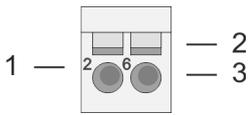
Data



Please use copper wire only!

$U_{max}$	30V DC
$I_{max}$	10A
Cross section	0.08 ... 1.5mm <sup>2</sup> (AWG 28 ... 16)
Stripping length	10mm

Wiring procedure



- 1 Pin number at the connector
- 2 Opening for screwdriver
- 3 Connection hole for wire



**CAUTION**

**Danger of injury from electrical shock and damage to the unit!**

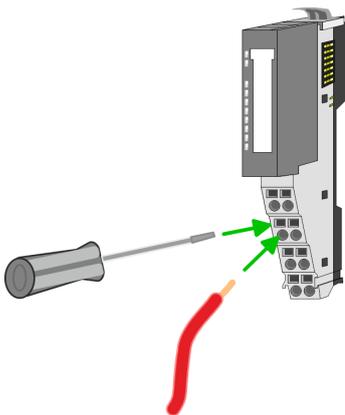
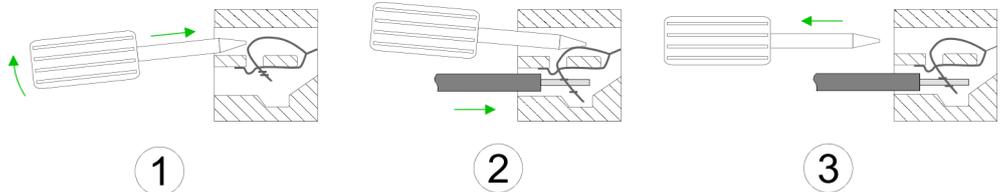
Put the System SLIO in a safe, powered down state before starting installation, disassembly or wiring of the System SLIO modules!



**CAUTION**

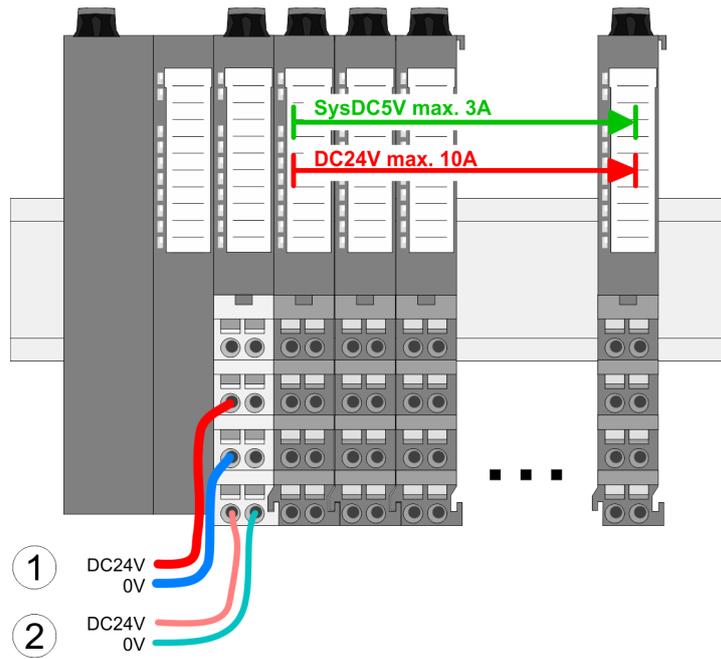
**Consider temperature for external cables!**

Cables may experience temperature increase due to system heat dissipation. Thus the cabling specification must be chosen 25°C above ambient temperature!



1. Insert a suited screwdriver at an angle into the square opening as shown. Press and hold the screwdriver in the opposite direction to open the contact spring.
2. Insert the stripped end of wire into the round opening. You can use wires with a cross section of 0.08mm<sup>2</sup> up to 1.5mm<sup>2</sup>
3. By removing the screwdriver, the wire is securely fixed via the spring contact to the terminal.

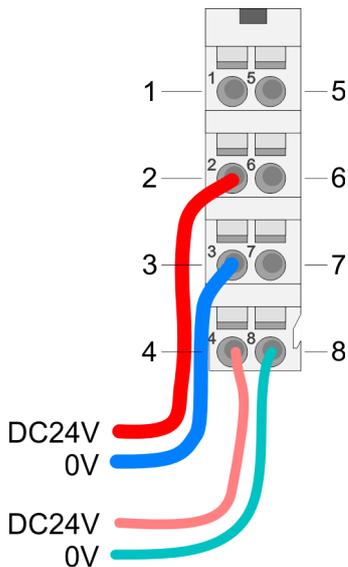
Standard wiring



- (1) DC 24V for power section supply I/O area (max. 10A)
- (2) DC 24V for electronic power supply bus coupler and I/O area

PM - Power module

For wires with a core cross-section of 0.08mm<sup>2</sup> up to 1.5mm<sup>2</sup>.



Pos.	Function	Type	Description
1	---	---	not connected
2	DC 24V	I	DC 24V for power section supply
3	0V	I	GND for power section supply
4	Sys DC 24V	I	DC 24V for electronic power supply
5	---	---	not connected
6	DC 24V	I	DC 24V for power section supply
7	0V	I	GND for power section supply
8	Sys 0V	I	GND for electronic power supply

I: Input



**CAUTION**

Since the power section supply is not internally protected, it is to be externally protected with a fuse, which corresponds to the maximum current. This means max. 10A is to be protected by a 10A fuse (fast) respectively by a line circuit breaker 10A characteristics Z and should be UL approved!



*The electronic power section supply is internally protected against higher voltage by fuse. The fuse is within the power module. If the fuse releases, its electronic module must be exchanged!*

**Fusing**

- The power section supply is to be externally protected with a fuse, which corresponds to the maximum current. This means max. 10A is to be protected with a 10A fuse (fast) respectively by a line circuit breaker 10A characteristics Z and should be UL approved!
  - For modules with positive logic (PNP), place the fuse on the positive connector.
  - For modules with negative logic (NPN), place the fuse on the negative connector.
  - For mixed logic, one fuse must be placed on the negative and one on the positive connector.
- It is recommended to externally protect the electronic power supply for head modules and I/O area with a 2A fuse (fast) respectively by a line circuit breaker 2A characteristics Z and should be UL approved.
- The electronic power supply for the I/O area of the power module 007-1AB10 should also be externally protected with a 1A fuse (fast) respectively by a line circuit breaker 1A characteristics Z and should be UL approved.

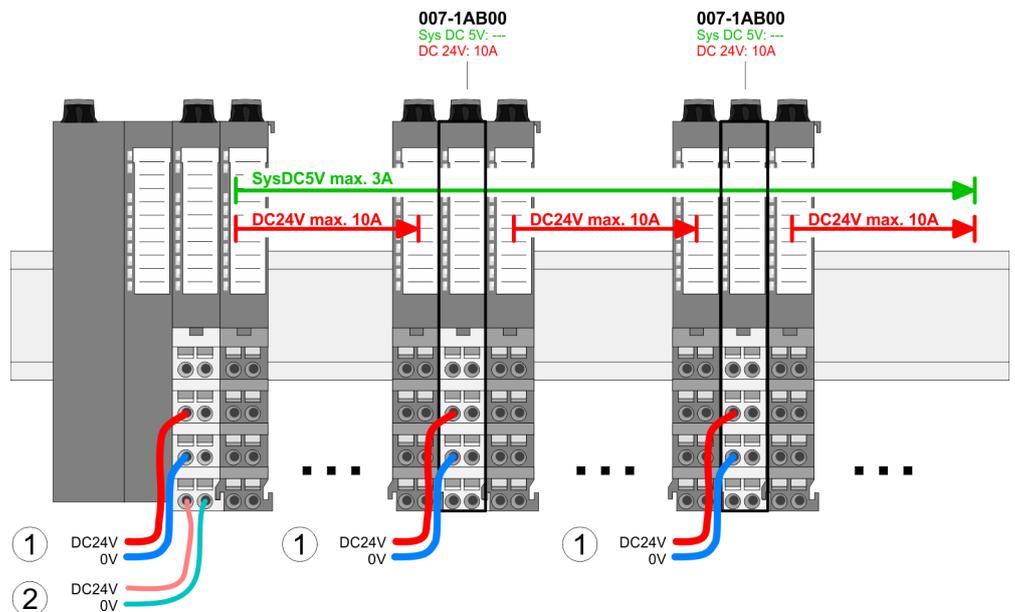
**State of the electronic power supply via LEDs**

After PowerON of the System SLIO the LEDs RUN respectively MF get on so far as the sum current does not exceed 3A. With a sum current greater than 3A the LEDs may not be activated. Here the power module with the order number 007-1AB10 is to be placed between the peripheral modules.

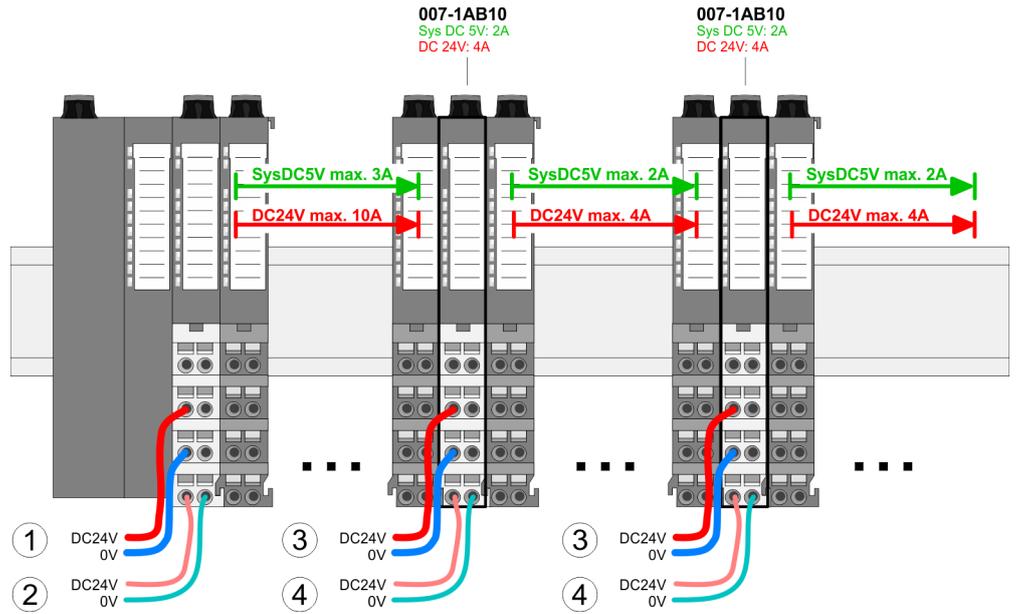
**Deployment of the power modules**

- If the 10A for the power section supply is no longer sufficient, you may use the power module with the order number 007-1AB00. So you have also the possibility to define isolated groups.
- The power module with the order number 007-1AB10 is to be used if the 3A for the electronic power supply at the backplane bus is no longer sufficient. Additionally you get an isolated group for the DC 24V power section supply with max. 4A.
- By placing the power module 007-1AB10 at the following backplane bus modules may be placed with a sum current of max. 2A. Afterwards a power module is to be placed again. To secure the power supply, the power modules may be mixed used.

**Power module 007-1AB00**



Power module 007-1AB10

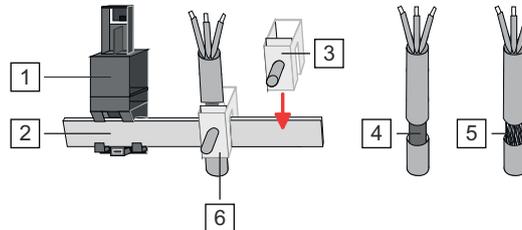


- (1) DC 24V for power section supply I/O area (max. 10A)
- (2) DC 24V for electronic power supply bus coupler and I/O area
- (3) DC 24V for power section supply I/O area (max. 4A)
- (4) DC 24V for electronic power supply I/O area

## 2.9 Shielding

### Overview

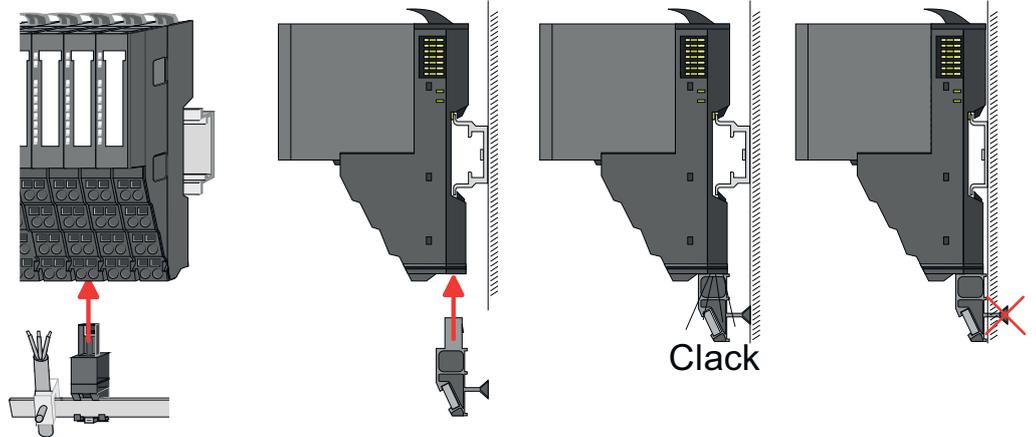
Shielding is required for interference-free signal transmission. This weakens electrical, magnetic or electromagnetic interference fields. To attach the shield the mounting of shield bus carriers are necessary. The shield bus carrier (available as accessory) serves to carry the shield bus to connect cable shields. → [Chap. 2.14.2 'Installation guidelines' ...page 41](#)



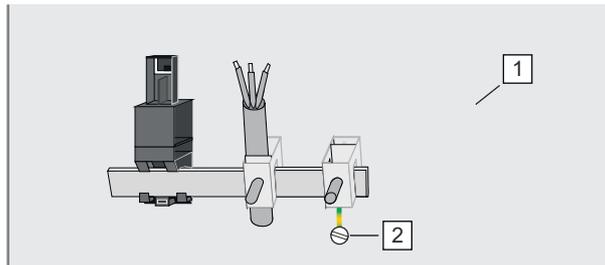
- ① Shield bus carrier
- ② Shield bus (10mm x 3mm)
- ③ Shield clamp
- ④ Cable shield with metal foil
- ⑤ Cable shield with wire mesh (close-meshed)
- ⑥ Cable shield mounted with shield clamp

**Shield attachment**

1. → System SLIO head and 8x periphery modules have a carrier hole for the shield bus carrier. Push the shield bus carrier, until they engage into the module. With a flat mounting rail for adaptation to a flat mounting rail you may remove the spacer of the shield bus carrier.
2. → Put your shield bus into the shield bus carrier.



3. → Attach the cables with the accordingly stripped cable screen and fix it by the shield clamp with the shield bus.
4. → The shield bus must always be earthed. Keep all cable connections as short as possible. To earth the shield bus, connect a PE conductor to the shield bus via a shield clamp and screw it to the base plate as close as possible and with low impedance.



- 1 Base plate
- 2 PE conductor screwed to base plate

## 2.10 Demounting 8x periphery modules

### Proceeding

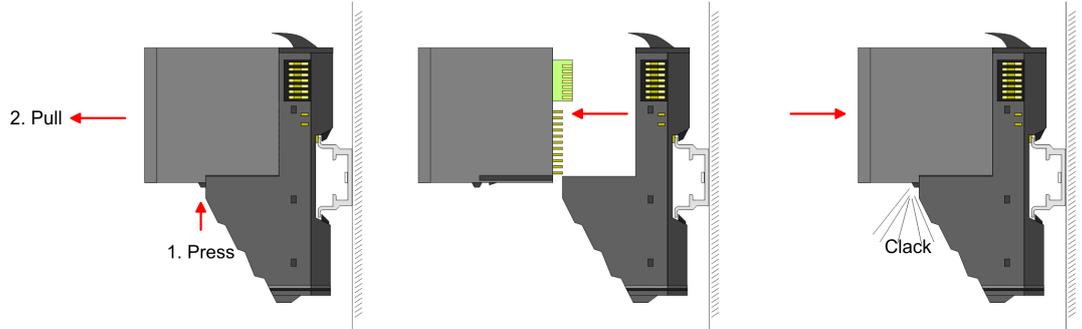
#### Exchange of an electronic module



#### CAUTION

Put the System SLIO in a safe, powered down state before starting disassembly!

1. Power-off your system.



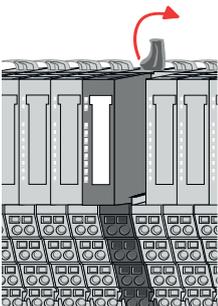
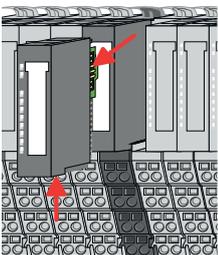
2. For the exchange of a electronic module, the electronic module may be pulled forward after pressing the unlocking lever at the lower side of the module.
3. For installation plug the new electronic module guided by the strips at the lower side until this engages to the terminal module.
  - ➔ Now you can bring your system back into operation.



#### Easy Maintenance

'Easy Maintenance' means the support for adding and removing electronic modules during operation without having to restart the system. If this is supported by your head module, you will find more detailed information on this in the "Deployment" chapter. ➔ Chap. 2.12 'Easy Maintenance' ...page 37

#### Exchange of a periphery module

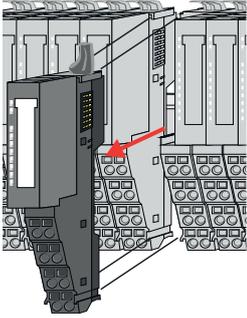


1. Power-off your system.
2. Remove if exists the wiring of the module.
- 3.

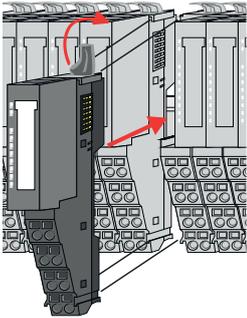


For demounting and exchange of a (head) module or a group of modules, due to mounting reasons you always have to remove the electronic module right beside. After mounting it may be plugged again.

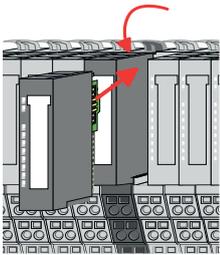
3. Press the unlocking lever at the lower side of the just mounted right module and pull it forward.
4. Turn the locking lever of the module to be exchanged upwards.



5. Pull the module.
6. For mounting turn the locking lever of the module to be mounted upwards.

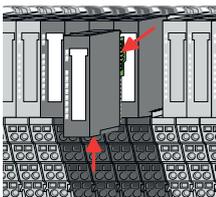


7. To mount the module put it to the gap between the both modules and push it, guided by the stripes at both sides, to the mounting rail.
8. Turn the locking lever downward, again.



9. Plug again the electronic module, which you have removed before.
10. Wire your module.
  - ➔ Now you can bring your system back into operation.

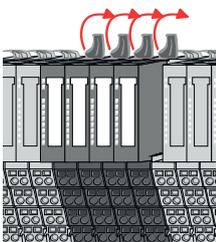
**Exchange of a module group**



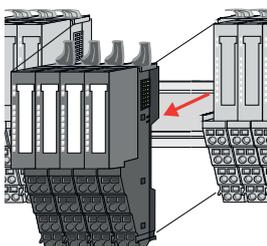
1. Power-off your system.
2. Remove if exists the wiring of the module group.
- 3.

**i** For demounting and exchange of a (head) module or a group of modules, due to mounting reasons you always have to remove the electronic module right beside. After mounting it may be plugged again.

Press the unlocking lever at the lower side of the just mounted right module near the module group and pull it forward.

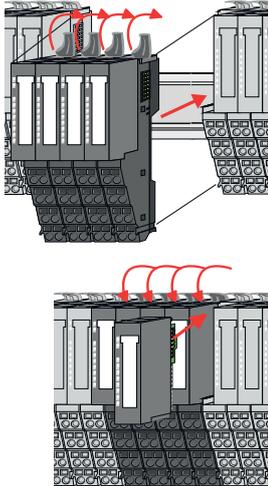


4. Turn all the locking lever of the module group to be exchanged upwards.



5. Pull the module group forward.
6. For mounting turn all the locking lever of the module group to be mounted upwards.

Demounting 16x periphery modules



7. To mount the module group put it to the gap between the both modules and push it, guided by the stripes at both sides, to the mounting rail.
8. Turn all the locking lever downward, again.
9. Plug again the electronic module, which you have removed before.
10. Wire your module group.
  - ➔ Now you can bring your system back into operation.

## 2.11 Demounting 16x periphery modules

### Proceeding

#### Exchange of an electronic unit



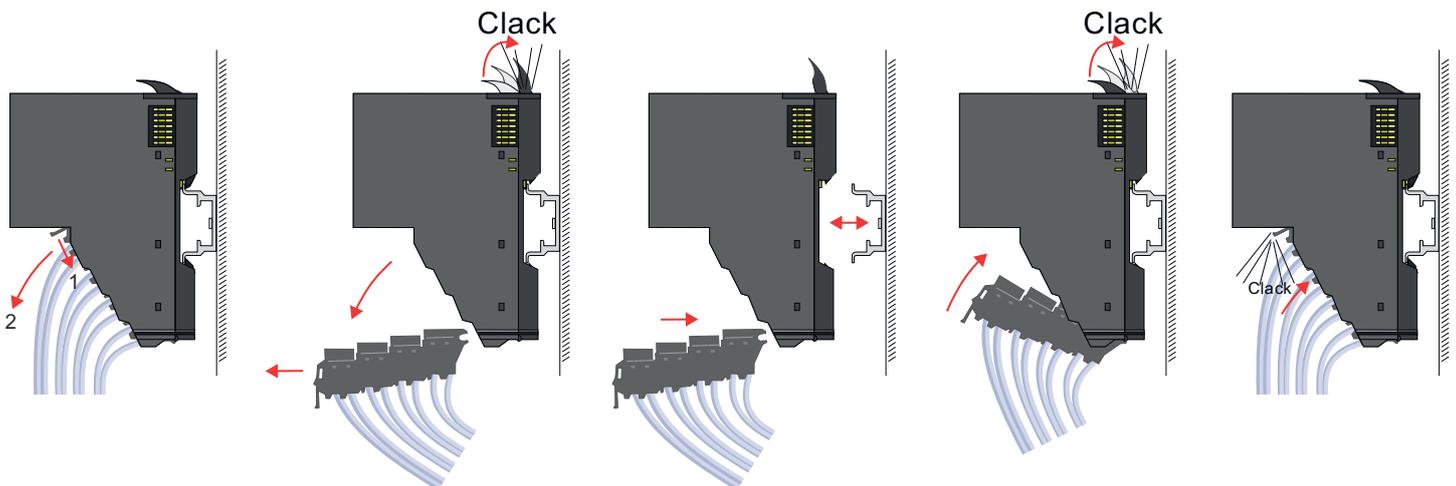
**CAUTION**

Put the System SLIO in a safe, powered down state before starting disassembly!

1. Power-off your system.
2. To replace an electronic unit, you can push down and pull off the terminal block after releasing the lock.

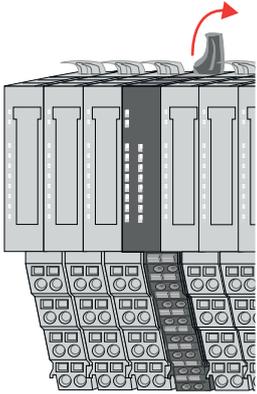
To mount the terminal block, place it horizontally on the lower side of the electronic unit and push it towards the electronic unit until it clicks into place.

➔ Now you can bring your system back into operation.



#### Exchange of a 16x periphery module

1. Power-off your system.
2. Remove if exists the wiring of the module respectively the wired terminal block.

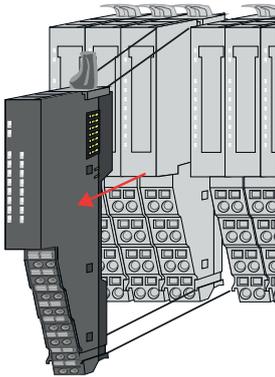


3. →



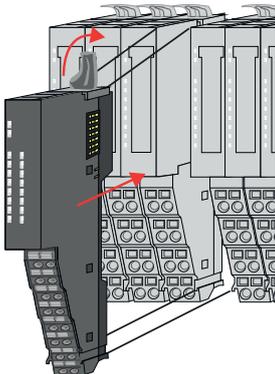
*In contrast to 8x periphery modules, you can directly demount and mount 16x periphery modules.*

Turn the locking lever of the module to be exchanged upwards.

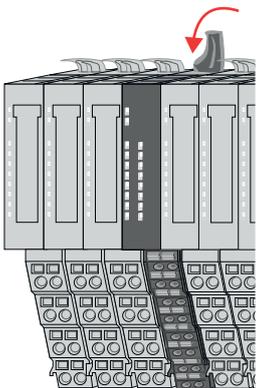


4. → Pull the module.

5. → For mounting turn the locking lever of the module to be mounted upwards.



6. → To mount the module put it to the gap between the both modules and push it, guided by the stripes at both sides, to the mounting rail.



7. → Turn the locking lever downward, again.

8. → Wire your module respectively plug the wired terminal block again.

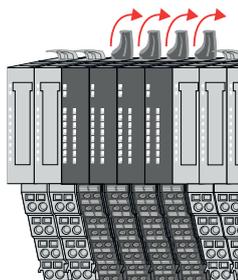
➔ Now you can bring your system back into operation.

### Exchange of a module group

1. → Power-off your system.

2. → Remove if exists the wiring of the module group respectively the wired terminal blocks.

Demounting 16x periphery modules

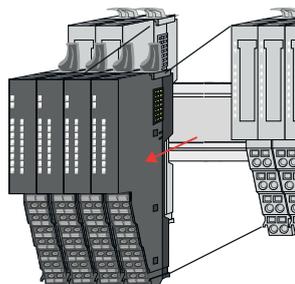


3. ➔



*In contrast to 8x periphery modules, you can directly demount and mount 16x periphery modules.*

Turn all the locking lever of the module group to be exchanged upwards.

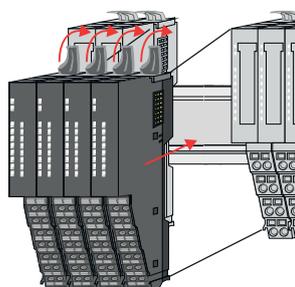


4. ➔

Pull the module group forward.

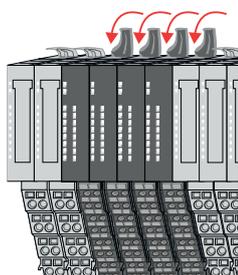
5. ➔

For mounting turn all the locking lever of the module group to be mounted upwards.



6. ➔

To mount the module group put it to the gap between the both modules and push it, guided by the stripes at both sides, to the mounting rail.



7. ➔

Turn all the locking lever downward, again.

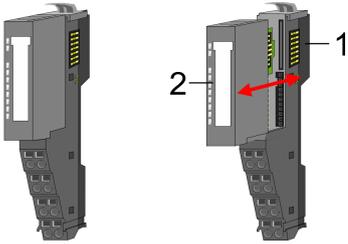
8. ➔

Wire your module group respectively plug the wired terminal blocks again.

➔ Now you can bring your system back into operation.

## 2.12 Easy Maintenance

### Overview



- 1 Terminal module
- 2 Electronic module

*Easy Maintenance* means the support for adding and removing an electronic module during operation without having to restart the system. Here the following behavior is shown by the example of a CPU:

- Electronic module is removed
  - The CPU detects a module failure on the backplane bus.
  - Diagnostic message *'System SLIO bus failure' (0x39D0)* is triggered.
  - OB 86 is called. If this is not available, the CPU switches to STOP otherwise it remains in RUN.
  - The SF LED of the CPU lights up.
  - The I/O data of all modules become invalid.
- Identical electronic module is plugged
  - The CPU detects the module return on the backplane bus.
  - The SF-LED of the CPU gets off.
  - All RUN LEDs on the modules get on and the MF LEDs get off.
  - Diagnostic message *'System SLIO bus recovery' (0x38D0)* is triggered.
  - OB 86 is called. If this is not available, the CPU switches to STOP otherwise it remains in RUN.
  - The I/O data of all modules become valid again.
- Wrong electronic module is plugged
  - The CPU detects the wrong module.
  - Diagnostic message *'System SLIO bus recovery, but expected configuration does not match actual configuration' (0x38D1)* is triggered.
  - The SF LED of the CPU remains on.
  - The MF LED of the wrong module flashes.
  - OB 86 is called. If this is not available, the CPU switches to STOP otherwise it remains in RUN.
  - With the exception of the wrong module, the I/O data of all modules become valid again.



### CAUTION

Please note that only electronic modules may be exchanged during operation! Replacing an 8x or 16x periphery module during operation can damage the module and the system!



Please note that the CPU switches to STOP, if there is no OB 86 configured when adding or removing System SLIO modules!

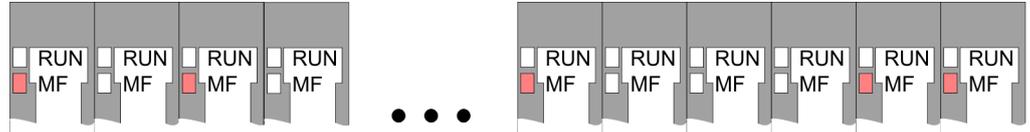
### 2.13 Trouble shooting - LEDs

**General**

Each module has the LEDs RUN and MF on its front side. Errors or incorrect modules may be located by means of these LEDs.

In the following illustrations flashing LEDs are marked by ☼.

**Sum current of the electronic power supply exceeded**

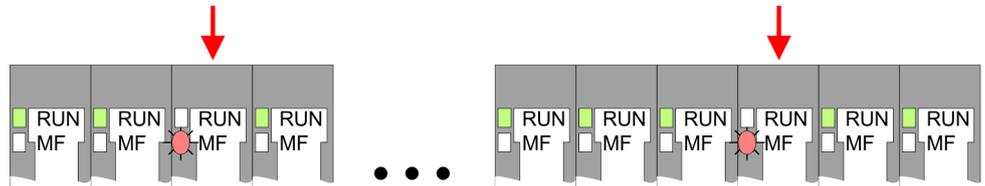


*Behavior:* After PowerON the RUN LED of each module is off and the MF LED of each module is sporadically on.

*Reason:* The maximum current for the electronic power supply is exceeded.

*Remedy:* As soon as the sum current of the electronic power supply is exceeded, always place the power module 007-1AB10. → [Chap. 2.8 'Wiring power modules' ...page 26](#)

**Error in configuration**

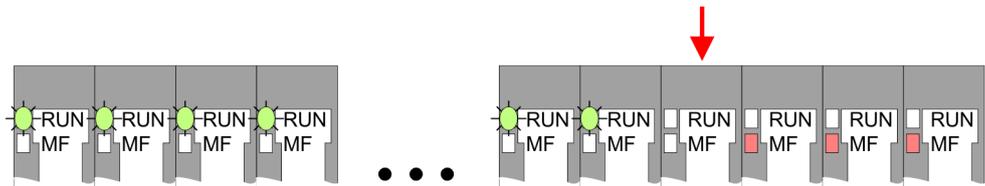


*Behavior:* After PowerON the MF LED of one module respectively more modules flashes. The RUN LED remains off.

*Reason:* At this position a module is placed, which does not correspond to the configured module.

*Remedy:* Match configuration and hardware structure.

**Module failure**



*Behavior:* After PowerON all of the RUN LEDs up to the defective module are flashing. With all following modules the MF LED is on and the RUN LED is off.

*Reason:* The module on the right of the flashing modules is defective.

*Remedy:* Replace the defective module.

## 2.14 Industrial security and installation guidelines

### 2.14.1 Industrial security in information technology

#### Latest version

This chapter can also be found as a guide *'Industrial IT Security'* in the *'Download Center'* of [www.yaskawa.eu.com](http://www.yaskawa.eu.com)

#### Hazards

The topic of data security and access protection has become increasingly important in the industrial environment. The increased networking of entire industrial systems to the network levels within the company together with the functions of remote maintenance have all served to increase vulnerability. Hazards can arise from:

- Internal manipulation such as technical errors, operating and program errors and deliberate program or data manipulation.
- External manipulation such as software viruses, worms and trojans.
- Human carelessness such as password phishing.

#### Precautions

The most important precautions to prevent manipulation and loss of data security in the industrial environment are:

- Encrypting the data traffic by means of certificates.
- Filtering and inspection of the traffic by means of VPN - "Virtual Private Networks".
- Identification of the user by "Authentication" via safe channels.
- Segmenting in protected automation cells, so that only devices in the same group can exchange data.
- Deactivation of unnecessary hardware and software.

#### Further Information

You can find more information about the measures on the following websites:

- Federal Office for Information Technology → [www.bsi.bund.de](http://www.bsi.bund.de)
- Cybersecurity & Infrastructure Security Agency → [us-cert.cisa.gov](http://us-cert.cisa.gov)
- VDI / VDE Society for Measurement and Automation Technology → [www.vdi.de](http://www.vdi.de)

### 2.14.1.1 Protection of hardware and applications

#### Precautions

- Do not integrate any components or systems into public networks.
  - Use VPN "Virtual Private Networks" for use in public networks. This allows you to control and filter the data traffic accordingly.
- Always keep your system up-to-date.
  - Always use the latest firmware version for all devices.
  - Update your user software regularly.
- Protect your systems with a firewall.
  - The firewall protects your infrastructure internally and externally.
  - This allows you to segment your network and isolate entire areas.
- Secure access to your plants via user accounts.
  - If possible, use a central user management system.
  - Create a user account for each user for whom authorization is essential.
  - Always keep user accounts up-to-date and deactivate unused user accounts.
- Secure access to your plants via secure passwords.
  - Change the password of a standard login after the first start.
  - Use strong passwords consisting of upper/lower case, numbers and special characters. The use of a password generator or manager is recommended.
  - Change the passwords according to the rules and guidelines that apply to your application.
- Deactivate inactive communication ports respectively protocols.
  - Only the communication ports that are used for communication should be activated.
  - Only the communication protocols that are used for communication should be activated.
- Consider possible defence strategies when planning and securing the system.
  - The isolation of components alone is not sufficient for comprehensive protection. An overall concept is to be drawn up here, which also provides defensive measures in the event of a cyber attack.
  - Periodically carry out threat assessments. Among others, a comparison is made here between the protective measures taken and those required.
- Limit the use of external storage media.
  - Via external storage media such as USB memory sticks or SD memory cards, malware can get directly into a system while bypassing a firewall.
  - External storage media or their slots must be protected against unauthorized physical access, e.g. by using a lockable control cabinet.
  - Make sure that only authorized persons have access.
  - When disposing of storage media, make sure that they are safely destroyed.
- Use secure access paths such as HTTPS or VPN for remote access to your plant.
- Enable security-related event logging in accordance with the applicable security policy and legal requirements for data protection.

### 2.14.1.2 Protection of PC-based software

#### Precautions

Since PC-based software is used for programming, configuration and monitoring, it can also be used to manipulate entire systems or individual components. Particular caution is required here!

- Use user accounts on your PC systems.
  - If possible, use a central user management system.
  - Create a user account for each user for whom authorization is essential.
  - Always keep user accounts up-to-date and deactivate unused user accounts.
- Protect your PC systems with secure passwords.
  - Change the password of a standard login after the first start.
  - Use strong passwords consisting of upper/lower case, numbers and special characters. The use of a password generator or manager is recommended.
  - Change the passwords according to the rules and guidelines that apply to your application.
- Enable security-related event logging in accordance with the applicable security policy and legal requirements for data protection.
- Protect your PC systems by security software.
  - Install virus scanners on your PC systems to identify viruses, trojans and other malware.
  - Install software that can detect phishing attacks and actively prevent them.
- Always keep your software up-to-date.
  - Update your operating system regularly.
  - Update your software regularly.
- Make regular backups and store the media at a safe place.
- Regularly restart your PC systems. Only boot from storage media that are protected against manipulation.
- Use encryption systems on your storage media.
- Perform security assessments regularly to reduce the risk of manipulation.
- Use only data and software from approved sources.
- Uninstall software which is not used.
- Disable unused services.
- Activate a password-protected screen lock on your PC systems.
- Always lock your PC systems as soon as you leave your PC workstation.
- Do not click any links that come from unknown sources. If necessary ask, e.g. on e-mails.
- Use secure access paths such as HTTPS or VPN for remote access to your PC system.

### 2.14.2 Installation guidelines

#### General

The installation guidelines contain information about the interference free deployment of a PLC system. There is the description of the ways, interference may occur in your PLC, how you can make sure the electromagnetic compatibility (EMC), and how you manage the isolation.

#### What does EMC mean?

Electromagnetic compatibility (EMC) means the ability of an electrical device, to function error free in an electromagnetic environment without being interfered respectively without interfering the environment.

The components are developed for the deployment in industrial environments and meets high demands on the EMC. Nevertheless you should project an EMC planning before installing the components and take conceivable interference causes into account.

**Possible interference causes**

Electromagnetic interferences may interfere your control via different ways:

- Electromagnetic fields (RF coupling)
- Magnetic fields with power frequency
- Bus system
- Power supply
- Protected earth conductor

Depending on the spreading medium (lead bound or lead free) and the distance to the interference cause, interferences to your control occur by means of different coupling mechanisms.

There are:

- galvanic coupling
- capacitive coupling
- inductive coupling
- radiant coupling

**Basic rules for EMC**

In the most times it is enough to take care of some elementary rules to guarantee the EMC. Please regard the following basic rules when installing your PLC.

- Take care of a correct area-wide grounding of the inactive metal parts when installing your components.
  - Install a central connection between the ground and the protected earth conductor system.
  - Connect all inactive metal extensive and impedance-low.
  - Please try not to use aluminium parts. Aluminium is easily oxidizing and is therefore less suitable for grounding.
- When cabling, take care of the correct line routing.
  - Organize your cabling in line groups (high voltage, current supply, signal and data lines).
  - Always lay your high voltage lines and signal respectively data lines in separate channels or bundles.
  - Route the signal and data lines as near as possible beside ground areas (e.g. suspension bars, metal rails, tin cabinet).
- Proof the correct fixing of the lead isolation.
  - Data lines must be shielded.
  - Analog lines must be shielded. When transmitting signals with small amplitudes the one sided laying of the isolation may be favourable.
  - Cables for frequency inverters, servo and stepper motors must be shielded.
  - Lay the line isolation extensively on an isolation/protected earth conductor rail directly after the cabinet entry and fix the isolation with cable clamps.
  - Make sure that the isolation/protected earth conductor rail is connected impedance-low with the cabinet.
  - Use metallic or metallised plug cases for isolated data lines.
- In special use cases you should appoint special EMC actions.
  - Consider to wire all inductivities with erase links.
  - Please consider luminescent lamps can influence signal lines.

- Create a homogeneous reference potential and ground all electrical operating supplies when possible.
  - Please take care for the targeted employment of the grounding actions. The grounding of the PLC serves for protection and functionality activity.
  - Connect installation parts and cabinets with your PLC in star topology with the isolation/protected earth conductor system. So you avoid ground loops.
  - If there are potential differences between installation parts and cabinets, lay sufficiently dimensioned potential compensation lines.

### Isolation of conductors

Electrical, magnetically and electromagnetic interference fields are weakened by means of an isolation, one talks of absorption. Via the isolation rail, that is connected conductive with the rack, interference currents are shunt via cable isolation to the ground. Here you have to make sure, that the connection to the protected earth conductor is impedance-low, because otherwise the interference currents may appear as interference cause.

When isolating cables you have to regard the following:

- If possible, use only cables with isolation tangle.
- The hiding power of the isolation should be higher than 80%.
- Normally you should always lay the isolation of cables on both sides. Only by means of the both-sided connection of the isolation you achieve high quality interference suppression in the higher frequency area. Only as exception you may also lay the isolation one-sided. Then you only achieve the absorption of the lower frequencies. A one-sided isolation connection may be convenient, if:
  - the conduction of a potential compensating line is not possible.
  - analog signals (some mV respectively  $\mu\text{A}$ ) are transferred.
  - foil isolations (static isolations) are used.
- With data lines always use metallic or metallised plugs for serial couplings. Fix the isolation of the data line at the plug rack. Do not lay the isolation on the PIN 1 of the plug bar!
- At stationary operation it is convenient to strip the insulated cable interruption free and lay it on the isolation/protected earth conductor line.
- To fix the isolation tangles use cable clamps out of metal. The clamps must clasp the isolation extensively and have well contact.
- Lay the isolation on an isolation rail directly after the entry of the cable in the cabinet.



#### CAUTION

#### Please regard at installation!

At potential differences between the grounding points, there may be a compensation current via the isolation connected at both sides.

Remedy: Potential compensation line

General data for the System SLIO

## 2.15 General data for the System SLIO

Conformity and approval		
Conformity		
CE	2014/35/EU	Low Voltage Directive
	2014/30/EU	EMC Directive
RoHS (EU)	2011/65/EU	Restriction of the use of certain hazardous substances in electrical and electronic equipment
UKCA	2016 No. 1101	Electrical Equipment (Safety) Regulations
	2016 No. 1091	Electromagnetic Compatibility Regulations
RoHS (UK)	2012 No. 3032	Use of Certain Hazardous Substances
Approval		
Certifications	-	Refer to technical data

Protection of persons and device protection		
Type of protection	-	IP20
Electrical isolation		
to the field bus	-	electrically isolated
to the process level	-	electrically isolated
Insulation resistance	-	-
Insulation voltage to reference earth		
Inputs / outputs	-	AC / DC 50V, test voltage AC 500V
Protective measures	-	against short circuit

Environmental conditions to EN 61131-2		
Operation		
Horizontal installation hanging	EN 61131-2	0...+60°C
Horizontal installation lying	EN 61131-2	0...+55°C
Vertical installation	EN 61131-2	0...+50°C
Air humidity	EN 60068-2-30	RH1 (without condensation, rel. humidity 10...95%)
Pollution	EN 61131-2	Degree of pollution 2
Installation altitude max.	-	2000m
Mechanical		
Oscillation	EN 60068-2-6	1g, 9Hz ... 150Hz
Shock	EN 60068-2-27	15g, 11ms

Mounting conditions		
Mounting place	-	In the control cabinet
Mounting position	-	Horizontal and vertical

EMC	Standard	Comment	
Emitted interference	EN 61000-6-4	Class A (Industrial area)	
Noise immunity zone B	EN 61000-6-2	Industrial area	
		EN 61000-4-2	ESD 8kV at air discharge (degree of severity 3), 4kV at contact discharge (degree of severity 2)
		EN 61000-4-3	HF field immunity (casing) 80MHz ... 1000MHz, 10V/m, 80% AM (1kHz) 1.4GHz ... 6GHz, 3V/m, 80% AM (1kHz)
		EN 61000-4-6	HF conducted 150kHz ... 80MHz, 10V, 80% AM (1kHz)
		EN 61000-4-4	Burst
		EN 61000-4-5	Surge <sup>1</sup>

1) Due to the high-energetic single pulses with Surge an appropriate external protective circuit with lightning protection elements like conductors for lightning and overvoltage is necessary.

### 2.15.1 Use in difficult operating conditions



**Without additional protective measures, the products must not be used in locations with difficult operating conditions; e.g. due to:**

- dust generation
- chemically active substances (corrosive vapors or gases)
- strong electric or magnetic fields

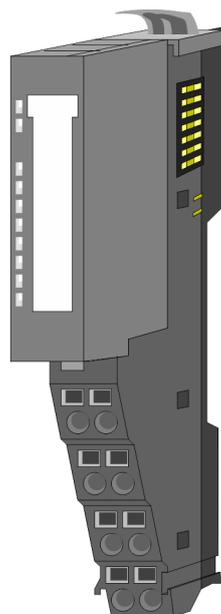
Structure

## 3 Hardware description

### 3.1 Properties

#### Features

- 2 counter 32bit (AB) invertible, DC 24V
- Counting frequency max 400kHz  
(AB 1/2/4-fold evaluation or pulse and direction)
- Comparison value, set value, input filter (configurable)
- Interrupt and diagnostics function with  $\mu$ s time stamp
- $\mu$ s time stamp for counter value (e.g. for speed calculation)

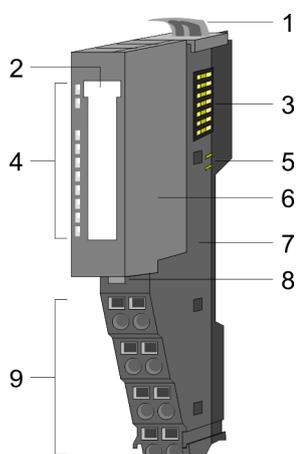


#### Order data

Type	Order number	Description
FM 050	050-1BB00	Counter module 2x32Bit DC 24V

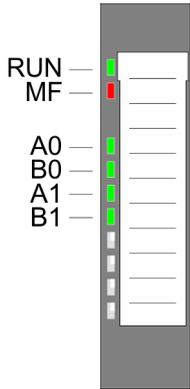
### 3.2 Structure

#### 050-1BB00



- 1 Locking lever terminal module
- 2 Labeling strip
- 3 Backplane bus
- 4 LED status indication
- 5 DC 24V power section supply
- 6 Electronic module
- 7 Terminal module
- 8 Locking lever electronic module
- 9 Terminal

Status indication

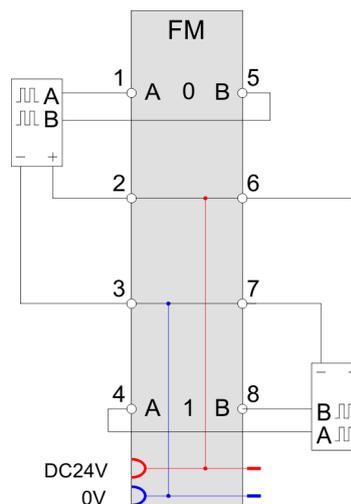
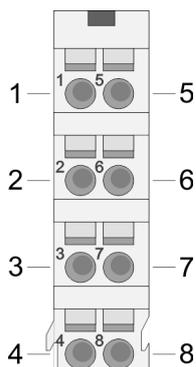


LED		Description	
RUN	MF		
grün	rot		
■	■		
●	○	Bus communication is OK Module status is OK	
●	●	Bus communication is OK Module status reports an error	
○	●	Bus communication is not possible Module status reports an error	
○	○	Error at bus power supply	
X	B	Error in configuration → <a href="#">Chap. 2.13 'Trouble shooting - LEDs' ...page 38</a>	
A0	green	●	Counter 0: Digital input 1 A0/pulse is set
B0	green	●	Counter 0: Digital input 5 B0/direction is set
A1	green	●	Counter 1: Digital input 4 A1/pulse is set
B1	green	●	Counter 1: Digital input 8 B1/direction is set

on: ● | off: ○ | blinks with 2Hz: B | not relevant: X

## Structure

## Pin assignment

For wires with a cross section of 0,08mm<sup>2</sup> up to 1,5mm<sup>2</sup>.

Pos.	Function	Type	Description
1	A0	I	Counter 0: A / pulse Pulse input for counter signal respectively track A of an encoder for 1-, 2- or 4-fold evaluation.
2	DC 24V	O	DC 24V for encoder
3	0V	O	GND
4	A1	I	Counter 1: A / pulse Pulse input for counter signal respectively track A of an encoder for 1-, 2- or 4-fold evaluation.
5	B0	I	Counter 0: B / direction direction signal respectively track B of an encoder (invertible via parameterization)
6	DC 24V	O	DC 24V for encoder
7	0V	O	GND
8	B1	I	Counter 1: B / direction direction signal respectively track B of an encoder (invertible via parameterization)

I: Input, O: Output

### 3.3 Technical data

<b>Order no.</b>	<b>050-1BB00</b>
Type	FM 050 - Counter module
Module ID	08C3 380A
<b>Current consumption/power loss</b>	
Current consumption from backplane bus	75 mA
Power loss	0.9 W
<b>Technical data digital inputs</b>	
Number of inputs	4
Cable length, shielded	100 m
Cable length, unshielded	-
Rated load voltage	DC 20.4...28.8 V
Reverse polarity protection of rated load voltage	-
Current consumption from load voltage L+ (without load)	15 mA
Rated value	DC 20.4...28.8 V
Input voltage for signal "0"	DC 0...5 V
Input voltage for signal "1"	DC 15...28.8 V
Input voltage hysteresis	-
Signal logic input	-
Frequency range	-
Input resistance	-
Input current for signal "1"	3 mA
Connection of Two-Wire-BEROs possible	✓
Max. permissible BERO quiescent current	0.5 mA
Input delay of "0" to "1"	0.8 µs
Input delay of "1" to "0"	0.8 µs
Number of simultaneously utilizable inputs horizontal configuration	4
Number of simultaneously utilizable inputs vertical configuration	4
Input characteristic curve	IEC 61131-2, type 1
Initial data size	12 Byte
<b>Technical data digital outputs</b>	
Number of outputs	-
Cable length, shielded	-
Cable length, unshielded	-
Rated load voltage	-
Current consumption from load voltage L+ (without load)	-
Output delay of "0" to "1"	-

## Technical data

Order no.	050-1BB00
Output delay of "1" to "0"	-
Minimum load current	-
Lamp load	-
Parallel switching of outputs for redundant control of a load	-
Parallel switching of outputs for increased power	-
Actuation of digital input	-
Switching frequency with resistive load	-
Switching frequency with inductive load	-
Switching frequency on lamp load	-
Internal limitation of inductive shut-off voltage	-
Short-circuit protection of output	-
Trigger level	-
Number of operating cycle of relay outputs	-
Switching capacity of contacts	-
Output data size	12 Byte
<b>Technical data counters</b>	
Number of counters	2
Counter width	32 Bit
Maximum input frequency	100 kHz
Maximum count frequency	400 kHz
Mode incremental encoder	✓
Mode pulse / direction	✓
Mode pulse	-
Mode frequency counter	-
Mode period measurement	-
Gate input available	-
Latch input available	-
Reset input available	-
Counter output available	-
<b>Status information, alarms, diagnostics</b>	
Status display	yes
Interrupts	yes, parameterizable
Process alarm	yes, parameterizable
Diagnostic interrupt	yes, parameterizable
Diagnostic functions	yes, parameterizable
Diagnostics information read-out	possible
Module state	green LED
Module error display	red LED

Order no.	050-1BB00
Channel error display	none
<b>Isolation</b>	
Between channels	-
Between channels of groups to	-
Between channels and backplane bus	✓
Between channels and power supply	-
Max. potential difference between circuits	-
Max. potential difference between inputs (Ucm)	-
Max. potential difference between Mana and Mintern (Uiso)	-
Max. potential difference between inputs and Mana (Ucm)	-
Max. potential difference between inputs and Mintern (Uiso)	-
Max. potential difference between Mintern and outputs	-
Insulation tested with	DC 500 V
<b>Datasizes</b>	
Input bytes	12
Output bytes	12
Parameter bytes	45
Diagnostic bytes	20
<b>Housing</b>	
Material	PPE / PPE GF10
Mounting	Profile rail 35 mm
<b>Mechanical data</b>	
Dimensions (WxHxD)	12.9 mm x 109 mm x 76.5 mm
Net weight	58 g
Weight including accessories	58 g
Gross weight	73 g
<b>Environmental conditions</b>	
Operating temperature	0 °C to 60 °C
Storage temperature	-25 °C to 70 °C
<b>Certifications</b>	
UL certification	yes
KC certification	yes
UKCA certification	yes
ChinaRoHS certification	yes

## 4 Deployment

### 4.1 Fast introduction

#### Counter range

Limits	Valid range of values
Lower counter limit	-2 147 483 648 ( $-2^{31}$ )
Upper counter limit	+2 147 483 647 ( $2^{31}-1$ )

The maximum counter frequency is 400kHz.

#### Address areas

#### Input area

At CPU, PROFIBUS and PROFINET the input area is embedded to the corresponding address area. More can be found in the corresponding manual.

IX Index for access via CANopen

SX Subindex for access via EtherCAT with index 6000h + EtherCAT-Slot

Addr.	Name	Bytes	Function	IX	SX
+0	CV_I	4	Counter 0: Counter value	5400h/s	01h
+4	CV_II	4	Counter 1: Counter value	5400h/s+1	02h
+8	CSTS_I	2	Counter 0: Counter status	5402h/s	03h
+10	CSTS_II	2	Counter 1: Counter status	5402h/s+1	04h

#### Output area

At CPU, PROFIBUS and PROFINET the output area is embedded to the corresponding address area. More can be found in the corresponding manual.

IX Index for access via CANopen

SX Subindex for access via EtherCAT with Index 7000h + EtherCAT-Slot

Addr.	Name	Bytes	Function	IX	SX
+0	CC_I	4	Counter 0: Comp. value	5600h/s	01h
+4	CC_II	4	Counter 1: Comp. value	5600h/s+1	02h
+8	CCTRL_I	2	Counter 0: Control word	5602h/s	03h
+10	CCTRL_II	2	Counter 1: Control word	5602h/s+1	04h

## CSTS\_I, CSTS\_II Counter status

Bit	Name	Function
0	-	reserved
1	STS_CTRL_COMP	is set when <i>comparison bit</i> is enabled
2	STS_SW-GATE	Status software gate (set when <i>SW gate</i> is active)
3...4	-	reserved
5	STS_GATE	Status internal gate (set when internal gate is active)
6	STS_COMP	Status <i>comparison bit</i>
7	STS_C_DN	Status set at counter direction backward
8	STS_C_UP	Status set at counter direction forward
9	STS_CMP <sup>1</sup>	Status comparison is set when the comparison condition is met.  If comparison is parameterized <i>never</i> , the bit is never set.
10	STS_END <sup>1</sup>	Status is set when <i>end value</i> was reached
11	STS_OFLW <sup>1</sup>	Status is set at overflow
12	STS_UFLW <sup>1</sup>	Status is set at underflow
13	STS_ZP <sup>1</sup>	Status is set at zero run
14...15	-	reserved

1) The bits remain set until reset with RES\_SET (bit 6 control word).

## CTRL\_I, CTRL\_II Control word

Bit	Name	Function
0	-	reserved
1	CTRL_COMP_SET	enables the <i>comparison bit</i>
2	SW_GATE_SET	sets the software gate
3...4	-	reserved
5	COUNTERVAL_SET	sets counter temporarily to the value of <i>set value</i>
6	RES_SET	resets the bits STS_CMP, STS_END, STS_OFLW, STS_UFLW and STS_ZP with edge 0-1
7...8	-	reserved
9	CTRL_COMP_RESET	disables the <i>comparison bit</i>
10	SW_GATE_RESET	resets the software gate
11...15	-	reserved

Fast introduction

## Parameters

DS Record set for access via CPU, PROFIBUS and PROFINET  
 IX Index for access via CANopen  
 SX Subindex for access via EtherCAT with Index 3100h + EtherCAT-Slot  
 More can be found in the according manual of your bus coupler.

Name	Bytes	Function	Default	DS	IX	SX
DIAG_EN	1	Diagnostic interrupt <sup>1</sup>	00h	00h	3100h	01h
CH0A	1	C0: Input frequency track A	02h	01h	3101h	02h
CH1B	1	C0: Input frequency track B	02h	01h	3102h	03h
CH2A	1	C1: Input frequency track A	02h	01h	3103h	04h
CH3B	1	C1: Input frequency track B	02h	01h	3104h	05h
INT_I	1	C0: Interrupt behavior <sup>1</sup>	00h	80h	3105h	06h
FCT_I	1	C0: Counter function <sup>1</sup>	00h	80h	3106h	07h
MODE2_I	1	C0: Counter mode 2 <sup>1</sup>	00h	80h	3107h	08h
MODE3_I	1	C0: Counter mode 3 <sup>1</sup>	00h	80h	3108h	09h
SET_I	4	C0: Set value	00h	81h	3109h... 310Ch	0Ah
END_I	4	C0: End value	00h	81h	310Dh... 3110h	0Bh
LOAD_I	4	C0: Load value	00h	81h	3111h... 3114h	0Ch
HYST_I	1	C0: Hysteresis	00h	81h	3115h	0Dh
CRES	1	reserved	00h	81h	3116h	0Eh
INT_II	1	C1: Interrupt behavior <sup>1</sup>	00h	82h	3117h	0Fh
FCT_II	1	C1: Counter function <sup>1</sup>	00h	82h	3118h	10h
MODE2_II	1	C1: Counter mode 2 <sup>1</sup>	00h	82h	3119h	11h
MODE3_II	1	C1: Counter mode 3 <sup>1</sup>	00h	82h	311Ah	12h
SET_II	4	C1: Set value	00h	83h	311Bh... 311Eh	13h
END_II	4	C1: End value	00h	83h	311Fh... 3112h	14h
LOAD_II	4	C1: Load value	00h	83h	3113h... 3116h	15h
HYST_II	1	C1: Hysteresis	00h	83h	3117h	16h
CRES	1	reserved	00h	83h	3118h	17h

1) This parameter may only be transferred at STOP state.

**Control counter**

The counter is controlled via the internal gate (I gate). The I gate corresponds to the software gate (SW gate).

**SW gate:**

Open (activate):

in user program by edge 0-1 SW\_GATE\_SET in the *control word*.

Close (deactivate):

in user program by edge 0-1 SW\_GATE\_RESET in the *control word*.

**Comparison bit**

The following behavior for the *comparison bit* STS\_COMP in the *counter status* may be set via the parameterization:

- No comparison: *Comparison bit* is not influenced
- *Counter value*  $\geq$  *comparison value*: *Comparison bit* is set
- *Counter value*  $\leq$  *comparison value*: *Comparison bit* is set
- *Counter value* = *comparison value*: *Comparison bit* is set

Please consider that the *comparison bit* may only be controlled, when the bit STS\_CTRL\_COMP in the *counter status* is set.

**4.2 In-/Output area****4.2.1 Input area 12byte****Input area**

At CPU, PROFIBUS and PROFINET the input area is embedded to the corresponding address area. More can be found in the corresponding manual.

IX Index for access via CANopen

SX Subindex for access via EtherCAT with index 6000h + EtherCAT-Slot

Addr.	Name	Bytes	Function	IX	SX
+0	CV_I	4	Counter 0: Counter value	5400h/s	01h
+4	CV_II	4	Counter 1: Counter value	5400h/s+1	02h
+8	CSTS_I	2	Counter 0: Counter status	5402h/s	03h
+10	CSTS_II	2	Counter 1: Counter status	5402h/s+1	04h

**CV\_I CV\_II Counter value**

The *counter value* always contains the current value of the corresponding counter.

In-/Output area &gt; Output area 12byte

**CSTS\_I CSTS\_II Counter status**

Bit	Name	Function
0	-	reserved
1	STS_CTRL_COMP	is set when <i>comparison bit</i> is enabled
2	STS_SW-GATE	Status software gate (set when <i>SW gate</i> is active)
3 ... 4	-	reserved
5	STS_GATE	Status internal gate (set when internal gate is active)
6	STS_COMP	Status <i>comparison bit</i>
7	STS_C_DN	Status set at counter direction backward
8	STS_C_UP	Status set at counter direction forward
9	STS_CMP <sup>1</sup>	Status comparison is set when the comparison condition is met.  If comparison is parameterized <i>never</i> , the bit is never set.
10	STS_END <sup>1</sup>	Status is set when end value was reached
11	STS_OFLW <sup>1</sup>	Status is set at overflow
12	STS_UFLW <sup>1</sup>	Status is set at underflow
13	STS_ZP <sup>1</sup>	Status is set at zero run
14 ... 15	-	reserved

<sup>1</sup>) The bits remain set until reset with RES\_SET (bit 6 control word).

**4.2.2 Output area 12byte****Output area**

At CPU, PROFIBUS and PROFINET the output area is embedded to the corresponding address area. More can be found in the corresponding manual.

IX Index for access via CANopen

SX Subindex for access via EtherCAT with Index 7000h + EtherCAT-Slot

Addr.	Name	Bytes	Function	IX	SX
+0	CV_I	4	Counter 0: Comp. value	5600h/s	01h
+4	CV_II	4	Counter 1: Comp. value	5600h/s+1	02h
+8	CSTS_I	2	Counter 0: Control word	5602h/s	03h
+10	CSTS_II	2	Counter 1: Control word	5602h/s+1	04h

**CC\_I CC\_II Comparison value**

With *comparison value* a value may be preset that may influence the *comparison bit* res. throw a process interrupt when compared with the recent counter value. The behavior of the *comparison bit* STS\_COMP in the *counter status* res. the process interrupt has to be set for counter 0 via the parameter INT\_I and INT\_II for counter 1.

**CCTRL\_I CCTRL\_II Control word**

Bit	Name	Function
0	-	reserved
1	CTRL_COMP_SET	enables the <i>comparison bit</i>
2	SW_GATE_SET	sets the software gate
3 ... 4	-	reserved
5	COUNTERVAL_SET	sets counter temporarily to the value of <i>set value</i>
6	RES_SET	resets the bits STS_CMP, STS_END, STS_OFLW, STS_UFLW and STS_ZP with edge 0-1
7 ... 8	-	reserved
9	CTRL_COMP_RESET	disables the <i>comparison bit</i>
10	SW_GATE_RESET	resets the software gate
11 ... 15	-	reserved

### 4.3 Parameter data

Via parameterization you may define among others:

- Interrupt behavior
- Input filter
- Counter operating mode res. behavior

DS Record set for access via CPU, PROFIBUS and PROFINET

IX Index for access via CANopen

SX Subindex for access via EtherCAT with Index 3100h + EtherCAT-Slot

More can be found in the according manual of your bus coupler.

## Parameter data

## Parameters

Name	Bytes	Function	Default	DS	IX	SX
DIAG_EN	1	Diagnostic interrupt <sup>1</sup>	00h	00h	3100h	01h
CH0A	1	C0: Input frequency track A	02h	01h	3101h	02h
CH1B	1	C0: Input frequency track B	02h	01h	3102h	03h
CH2A	1	C1: Input frequency track A	02h	01h	3103h	04h
CH3B	1	C1: Input frequency track B	02h	01h	3104h	05h
INT_I	1	C0: Interrupt behavior <sup>1</sup>	00h	80h	3105h	06h
FCT_I	1	C0: Counter function <sup>1</sup>	00h	80h	3106h	07h
MODE2_I	1	C0: Counter mode 2 <sup>1</sup>	00h	80h	3107h	08h
MODE3_I	1	C0: Counter mode 3 <sup>1</sup>	00h	80h	3108h	09h
SET_I	4	C0: Set value	00h	81h	3109h... 310Ch	0Ah
END_I	4	C0: End value	00h	81h	310Dh... 3110h	0Bh
LOAD_I	4	C0: Load value	00h	81h	3111h... 3114h	0Ch
HYST_I	1	C0: Hysteresis	00h	81h	3115h	0Dh
CRES	1	reserved	00h	81h	3116h	0Eh
INT_II	1	C1: Interrupt behavior <sup>1</sup>	00h	82h	3117h	0Fh
FCT_II	1	C1: Counter function <sup>1</sup>	00h	82h	3118h	10h
MODE2_II	1	C1: Counter mode 2 <sup>1</sup>	00h	82h	3119h	11h
MODE3_II	1	C1: Counter mode 3 <sup>1</sup>	00h	82h	311Ah	12h
SET_II	4	C1: Set value	00h	83h	311Bh... 311Eh	13h
END_II	4	C1: End value	00h	83h	311Fh... 3122h	14h
LOAD_II	4	C1: Load value	00h	83h	3123h... 3126h	15h
HYST_II	1	C1: Hysteresis	00h	83h	3127h	16h
CRES	1	reserved	00h	83h	3128h	17h

1) This parameter may only be transferred at STOP state.

**DIAG\_EN** Diagnostic interrupt

Byte	Bit 7...0
0	Diagnostic interrupt <ul style="list-style-type: none"> <li>■ 00h = disable</li> <li>■ 40h = enable</li> </ul>

- Here you activate res. de-activate the diagnostic function.

**CHxx** Input frequency

Byte	Function	Possible values
0	Input frequency C0 track A	<ul style="list-style-type: none"> <li>■ 02h: 100kHz</li> <li>■ 03h: 60kHz</li> <li>■ 04h: 30kHz</li> <li>■ 06h: 10kHz</li> <li>■ 07h: 5kHz</li> <li>■ 08h: 2kHz</li> <li>■ 09h: 1kHz</li> </ul> Other values are not permissible!
1	Input frequency C0 track B	
2	Input frequency C1 track A	
3	Input frequency C1 track B	

- *Input frequency* allows you to preset a filter for I1, I4, I5 and I8. With the help of filters you may e.g. filter signal peaks at a blurred input signal.

**INT\_I/II, C0/C1:** Interrupt behavior

Byte	Bit 7 ... 0
0	<i>Bit 5 ... 0: Interrupt behavior</i> <ul style="list-style-type: none"> <li>■ Bit 0: 0 (fix)</li> <li>■ Bit 1: 0 (fix)</li> <li>■ Bit 2: Proc. interrupt overflow</li> <li>■ Bit 3: Proc. interrupt underflow</li> <li>■ Bit 4: Proc. interrupt <i>comparison value</i></li> <li>■ Bit 5: Proc. interrupt <i>end value</i></li> <li>■ <i>Bit 7 ... 6: 0 (fix)</i></li> </ul>

- Setting the appropriate bit activates the associated process interrupt

**FCT\_I/II, C0/C1:** Counter function

Byte	Bit 7 ... 0
0	<ul style="list-style-type: none"> <li>■ <i>Bit 5 ... 0: Counter function</i> <ul style="list-style-type: none"> <li>- 000000b = Count endless</li> <li>- 000001b = Once: forward</li> <li>- 000010b = Once: backwards</li> <li>- 000100b = Once: no main direction</li> <li>- 001000b = Periodic: forward</li> <li>- 010000b = Periodic: backwards</li> <li>- 100000b = Periodic: no main direction</li> </ul> </li> <li>■ <i>Bit 7 ... 6: 0 (fix)</i></li> </ul>

Parameter data

MODE2\_I/II, C0/C1: Counter mode 2

Byte	Bit 7 ... 0
0	<ul style="list-style-type: none"> <li>■ <i>Bit 2 ... 0: Comparison bit is set</i> (... when following condition is met)                             <ul style="list-style-type: none"> <li>- 000b = never</li> <li>- 001b = <i>Counter value</i> ≥ <i>comparison value</i></li> <li>- 010b = <i>Counter value</i> ≤ <i>comparison value</i></li> <li>- 100b = <i>Counter value</i> = <i>comparison value</i></li> </ul> </li> <li>■ <i>Bit 3: Counter direction track B inverted</i> <ul style="list-style-type: none"> <li>- 0 = No (not inverted)</li> <li>- 1 = Yes (inverted)</li> </ul> </li> <li>■ <i>Bit 7 ... 4: 0 (fix)</i></li> </ul>

MODE3\_I/II, C0/C1: Counter mode 3

Byte	Bit 7 ... 0
0	<ul style="list-style-type: none"> <li>■ <i>Bit 2 ... 0: Signal evaluation</i> <ul style="list-style-type: none"> <li>- 000b = Counter de-activated</li> <li>- 001b = Rotary encoder single (at A and B)</li> <li>- 010b = Rotary encoder double (at A and B)</li> <li>- 011b = Rotary encoder quadruple (at A and B)</li> <li>- 100b = Direction (pulse at A and direction at B)</li> </ul> </li> <li>■ <i>Bit 6 ... 3: 0 (fix)</i></li> <li>■ <i>Bit 7: Gate function (internal gate)</i> <ul style="list-style-type: none"> <li>- 0 = abort</li> <li>- 1 = interrupt</li> </ul> </li> </ul>

- At de-activated counter the further parameter settings are ignored.
- With gate function "abort" counting begins again at the load value. With "interrupt" counting is continued with the count.

SET\_I/II, C0/C1: Set value

There is the possibility to preset each counter with a set *value*. The value is kept by the counter by a changing edge 0-1 of the bit COUNTERVAL\_SET in the *control word*.

LOAD\_I/II Load value, END\_I/II End value, C0/C1

You may set an upper and a lower limit by setting a *load value* as start and an *end value*.

HYST\_I/II, C0/C1: Hysteresis

The *hysteresis* serves the avoidance of many toggle processes of the output and/or the interrupt, if the *counter value* is in the range of the *comparison value*. You may set a range of 0 to 255. The settings 0 and 1 deactivate the *hysteresis*. The *hysteresis* influences zero run, comparison, over- and underflow.

## 4.4 Counter - Functions

### Overview

You may count forward and backwards and choose between the following counter functions:

- Count endless, e.g. distance measuring with incremental encoder
- Count once, e.g. count to a maximum limit
- Count periodic, e.g. count with repeated counter process

In the operating modes "Count once" and "Count periodic" you may define a counter range as start and end value via the parameterization. For every counter additional parameterizable functions are available like gate function, comparison, hysteresis and process interrupt.

### Main counting direction

Via the parameterization you have the opportunity to define a main counting direction for every counter. If "none" is chosen, the complete counting range is available:

Limits	Valid value range
Lower count limit	-2 147 483 648 ( $-2^{31}$ )
Upper count limit	+2 147 483 647 ( $2^{31}-1$ )

#### *Main counting direction forward*

Upper restriction of the count range. The counter counts 0 res. *load value* in positive direction until the parameterized *end value* -1 and jumps then back to the load value with the next following encoder pulse.

#### *Main counting direction backwards*

Lower restriction of the count range. The counter counts from the parameterized start-res. *load value* in negative direction to the parameterized *end value* +1 and jumps then back to the start value with the next following encoder pulse.

### Gate function abort/interrupt

An opening and closing of the SW gate abort or interrupts the count process.

#### *Abort count process*

The count process starts after closing and restart of the gate beginning with the *load value*.

#### *Interrupt count process*

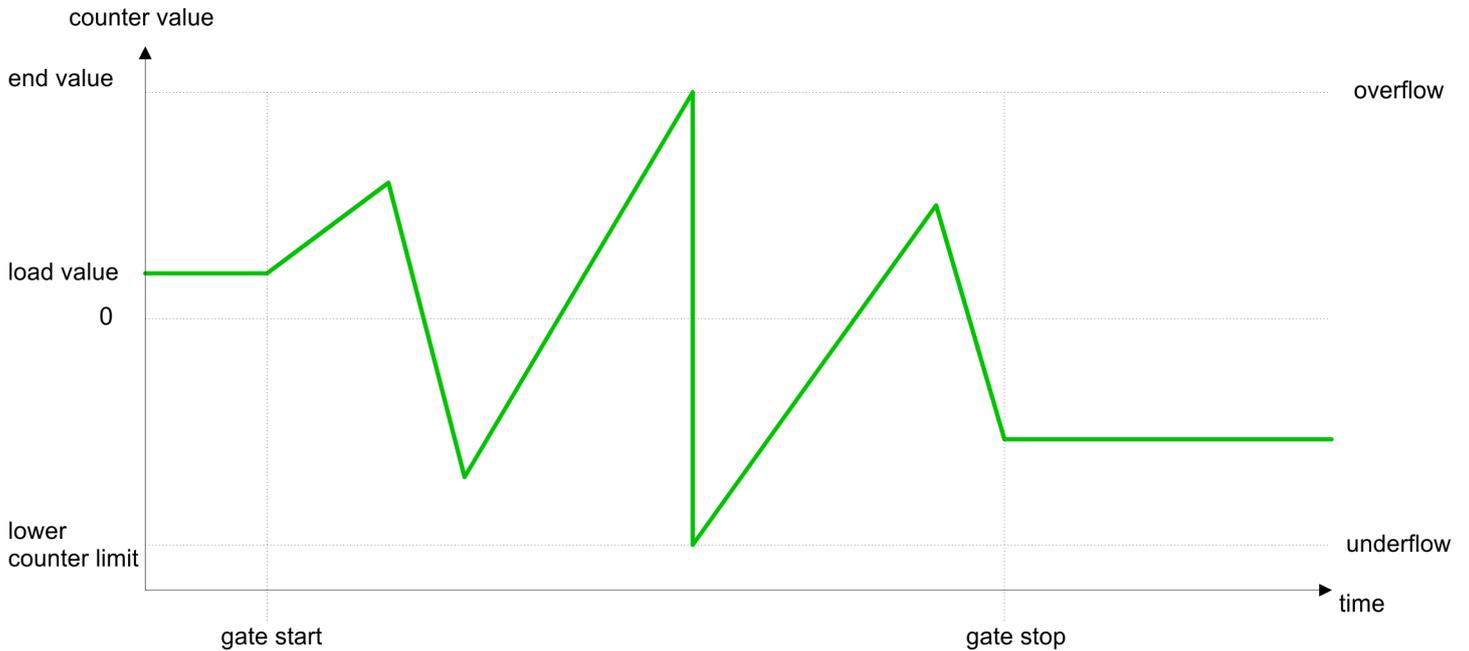
The count process continuous after closing and restart of the gate beginning with the last recent counter value.

**Count continuously**

In this operating mode, the counter counts from the load value. When the counter counts forward and reaches the upper count limit and another counting pulse in positive direction arrives, it jumps to the lower count limit and counts from there on. When the counter counts backwards and reaches the lower count limit and another counting pulse in negative direction arrives, it jumps to the upper count limit and counts from there on. The count limits are set to the maximum count range.

Limits	Valid value range
Lower count limit	-2 147 483 648 ( $-2^{31}$ )
Upper count limit	+2 147 483 647 ( $2^{31}-1$ )

With overflow or underflow the status bits STS\_OFLW respectively STS\_UFLW are set. These bits remain set until these are reset with RES\_STS. If enabled additionally a process interrupt is triggered.



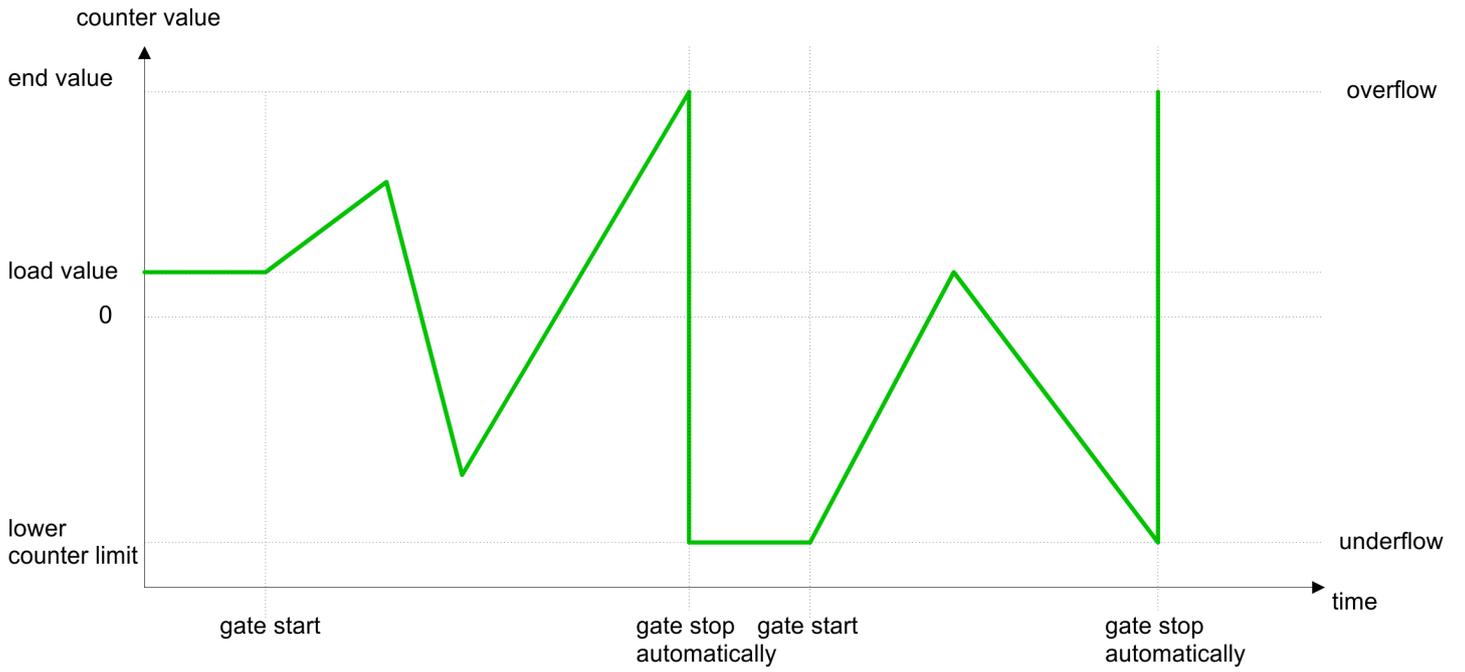
**Count Once**

*No main counting direction*

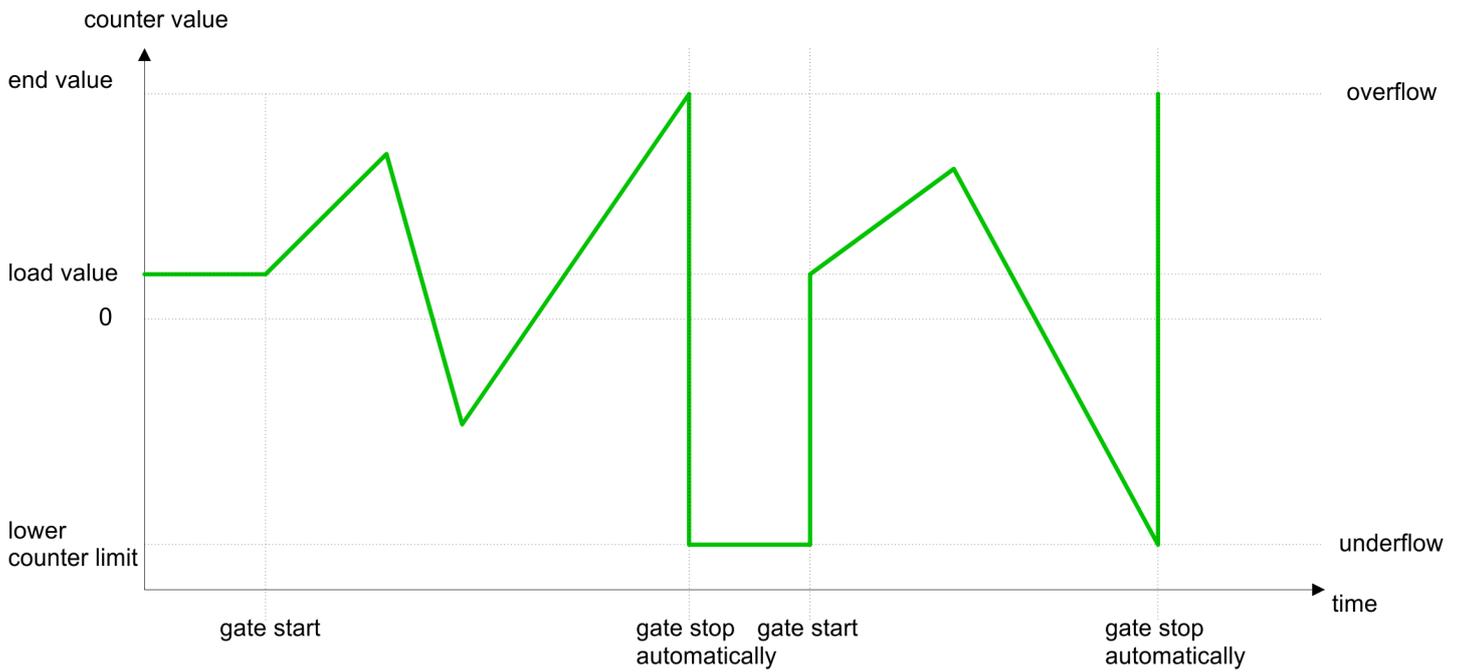
- The counter counts once starting with the *load value*.
- You may count forward or backwards.
- The count limits are set to the maximum count range.
- At over- or underflow at the count limits, the counter jumps to the according other count limit and the internal gate is automatically closed and the status bits STS\_OFLW respectively STS\_UFLW are set. If enabled additionally a process interrupt is triggered.
- To restart the count process, you have to re-open the internal gate.
- At interrupting gate control, the count process continuous with the last recent *counter value*.
- At aborting gate control, the counter starts with the *load value*.

Limits	Valid value range
Lower count limit	-2 147 483 648 ( $-2^{31}$ )
Upper count limit	+2 147 483 647 ( $2^{31} - 1$ )

*Interrupting gate control:*



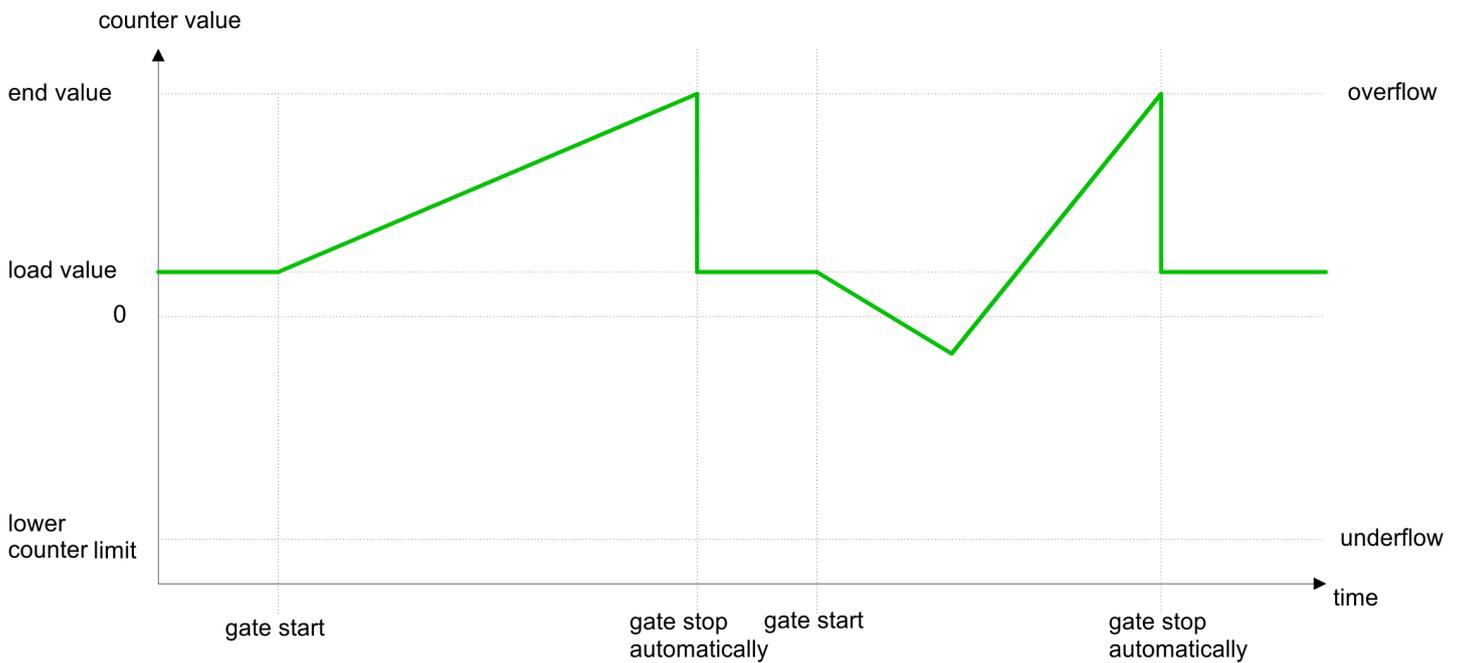
*Aborting gate control:*



*Main counting direction forward*

- The counter counts starting with the *load value*.
- When the counter reaches the end value -1 in positive direction, it jumps to the load value at the next positive count pulse and the gate is automatically closed.
- To restart the count process, you must create a positive edge of the gate. The counter starts with the load value.
- You may exceed the lower count limit.

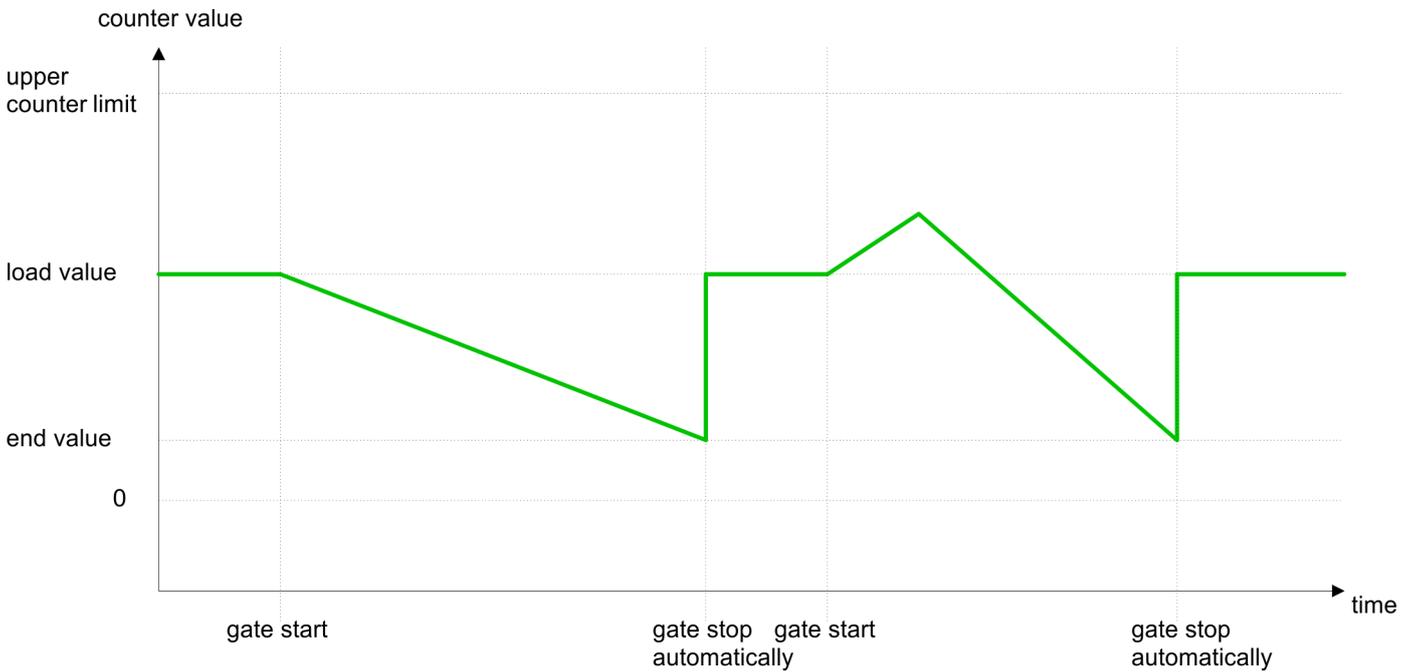
Limits	Valid value range
Limit value	-2 147 483 647 ( $-2^{31} + 1$ ) to +2 147 483 647 ( $2^{31} - 1$ )
Lower count limit	-2 147 483 648 ( $-2^{31}$ )



*Main counting direction backwards*

- The counter counts backwards starting with the *load value*.
- When the counter reaches the end value +1 in negative direction, it jumps to the load value at the next negative count pulse and the gate is automatically closed.
- To restart the count process, you must create a positive edge of the gate. The counter starts with the load value.
- You may exceed the upper count limit.

Limits	Valid value range
Limit value	-2 147 483 648 ( $-2^{31}$ ) to +2 147 483 646 ( $2^{31} - 2$ )
Upper count limit	+2 147 483 647 ( $2^{31} - 1$ )

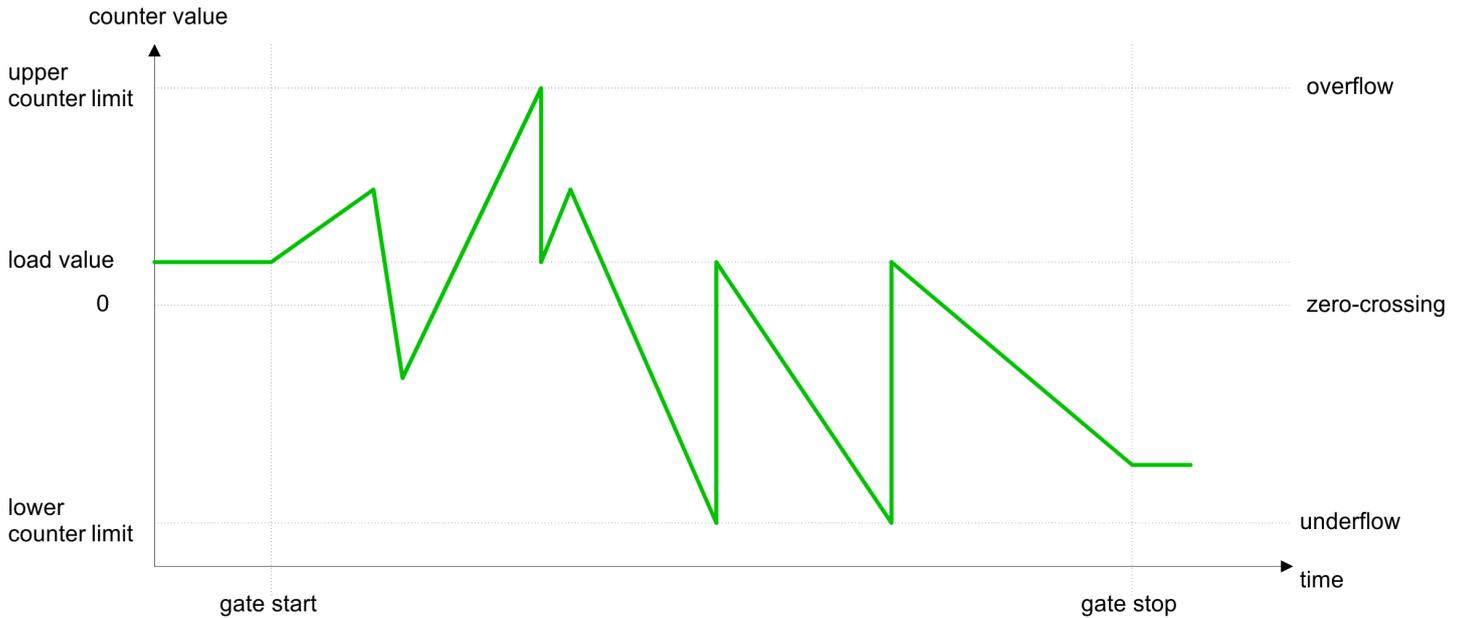


**Count Periodically**

*No main counting direction*

- The counter counts forward or backwards starting with the *load value*.
- At over- or underrun at the count limits, the counter jumps to the according other count limit and counts from there on.
- The count limits are set to the maximum count range.

Limits	Valid value range
Lower count limit	-2 147 483 648 ( $-2^{31}$ )
Upper count limit	+2 147 483 647 ( $2^{31} - 1$ )



*Main counting direction forward*

- The counter counts forward starting with the *load value*.
- When the counter reaches the end value  $-1$  in positive direction, it jumps to the load value at the next positive count pulse.
- You may exceed the lower count limit.

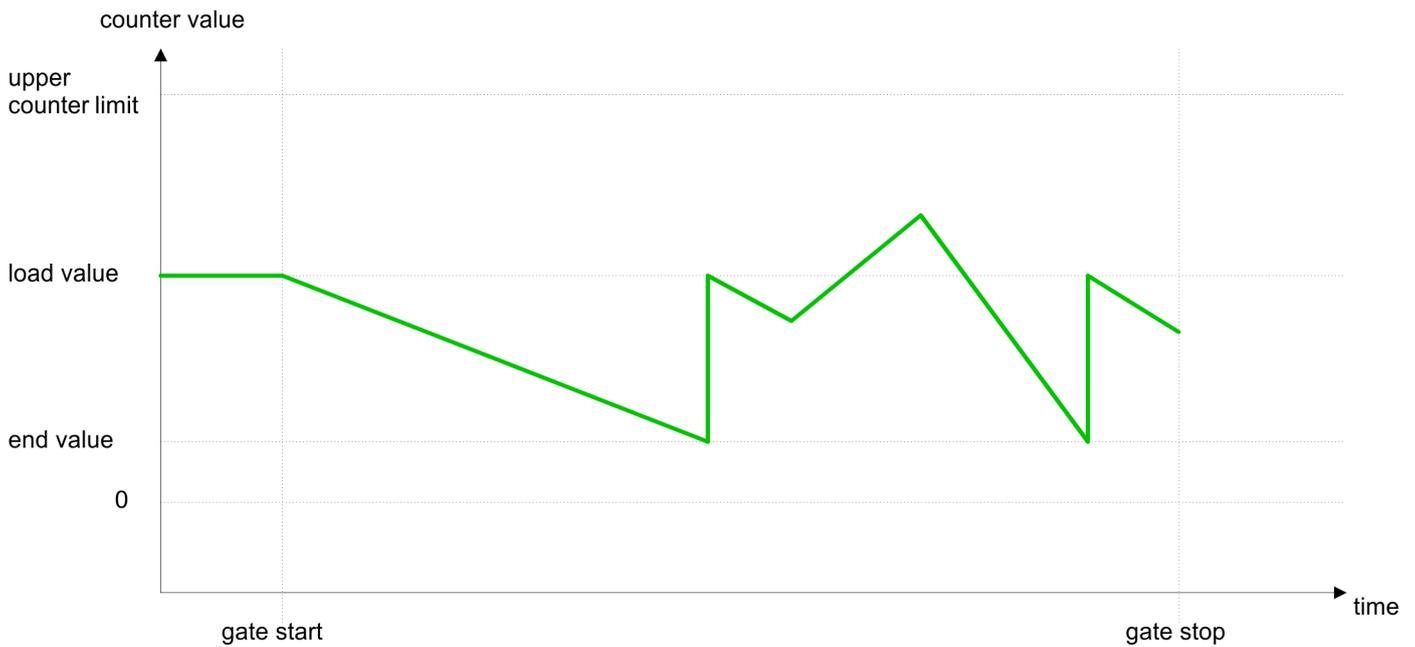
Limits	Valid value range
Limit value	$-2\ 147\ 483\ 647 (-2^{31} + 1)$ to $+2\ 147\ 483\ 647 (2^{31} - 1)$
Lower count limit	$-2\ 147\ 483\ 648 (-2^{31})$



*Main counting direction backwards*

- The counter counts backwards starting with the *load value*.
- When the counter reaches the *end value* + 1 in negative direction, it jumps to the *load value* at the next negative count pulse.
- You may exceed the upper count limit.

Limits	Valid value range
Limit value	-2 147 483 648 ( $-2^{31}$ ) to +2 147 483 646 ( $2^{31} - 2$ )
Upper count limit	+2 147 483 647 ( $2^{31} - 1$ )



## 4.5 Counter additional functions

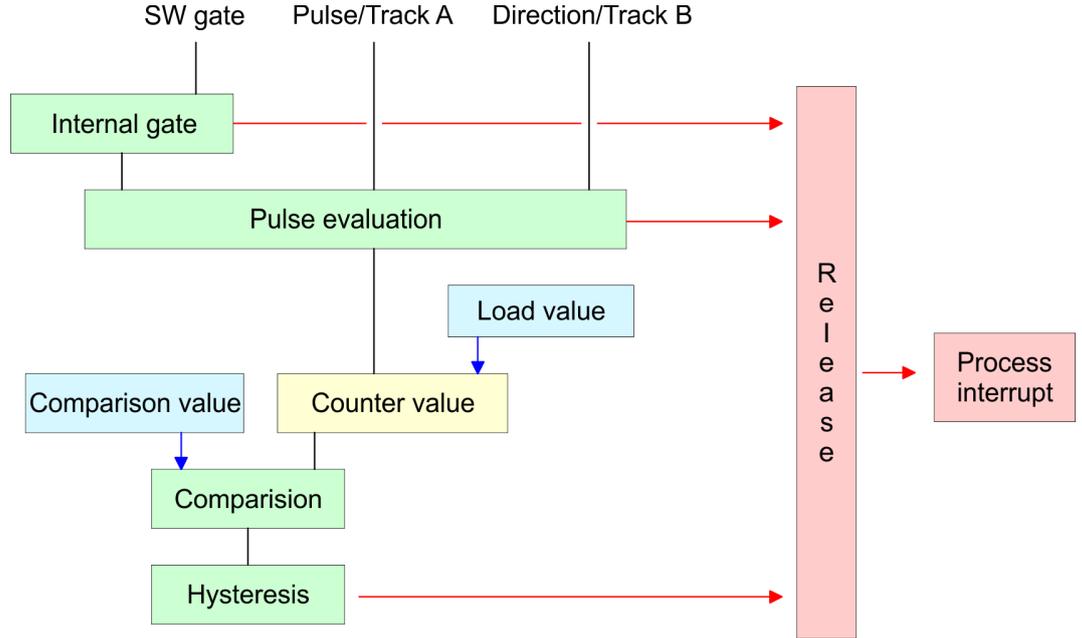
### Overview

The following additional functions may be set for each counter via the parameterization:

- Gate function
  - The gate function serves for the start, stop and interrupt of a count function.
- Comparison
  - You may set a *comparison value* that activates res. de-activates the digital output res. releases a process interrupt depending on the *counter value*.
- Hysteresis
  - The setting of a *hysteresis* avoids for example a high interrupt toggling when the value of an encoder signal shifts around a comparison value.

**Schematic structure**

The illustration shows how the additional functions influence the counting behavior. The following pages describe these functions in detail:



**Gate function**

The activation res. de-activation of the counter happens via an internal gate (I gate). The I gate corresponds to the software gate (SW gate). The SW gate is opened (activated) via your user application by an edge 0-1 of the bit SW\_GATE\_SET of the control word in the output area. The software gate is closed (de-activated) by an edge 0-1 of the bit SW\_GATE\_RESET. If the I gate was automatically closed at "counting once", so this may only be opened with an edge 0-1 on SW\_GATE\_SET. The following states influence the I gate:

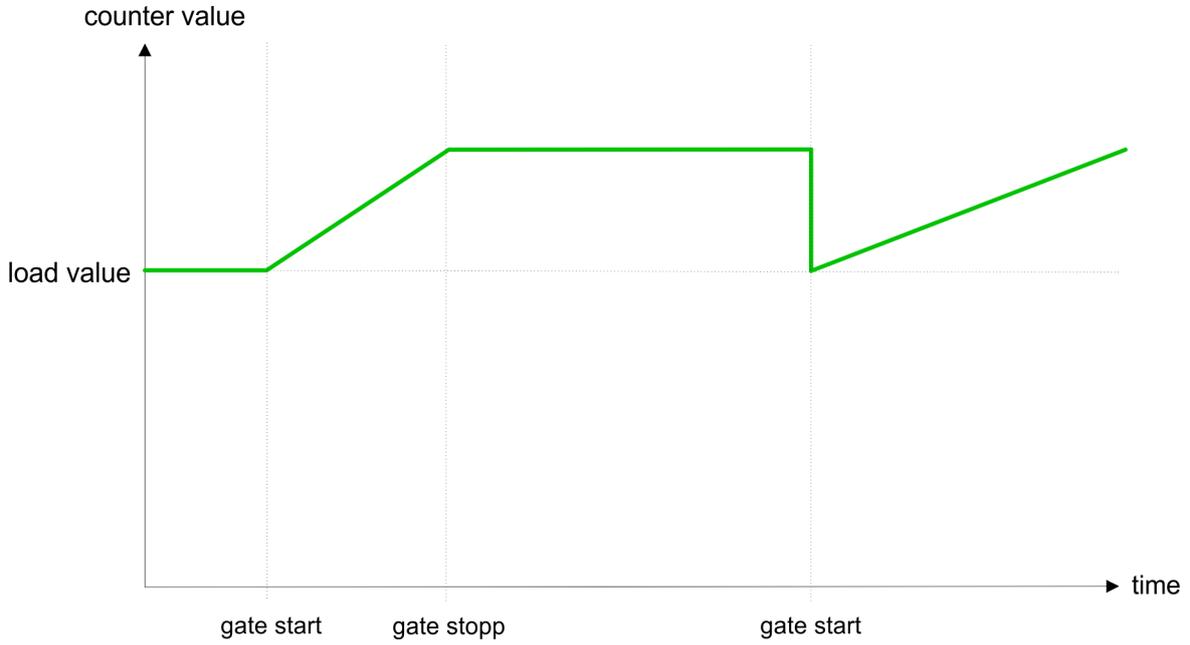
SW gate	influences I gate
0	0
1	1
with edge 0-1	1

Counter additional functions

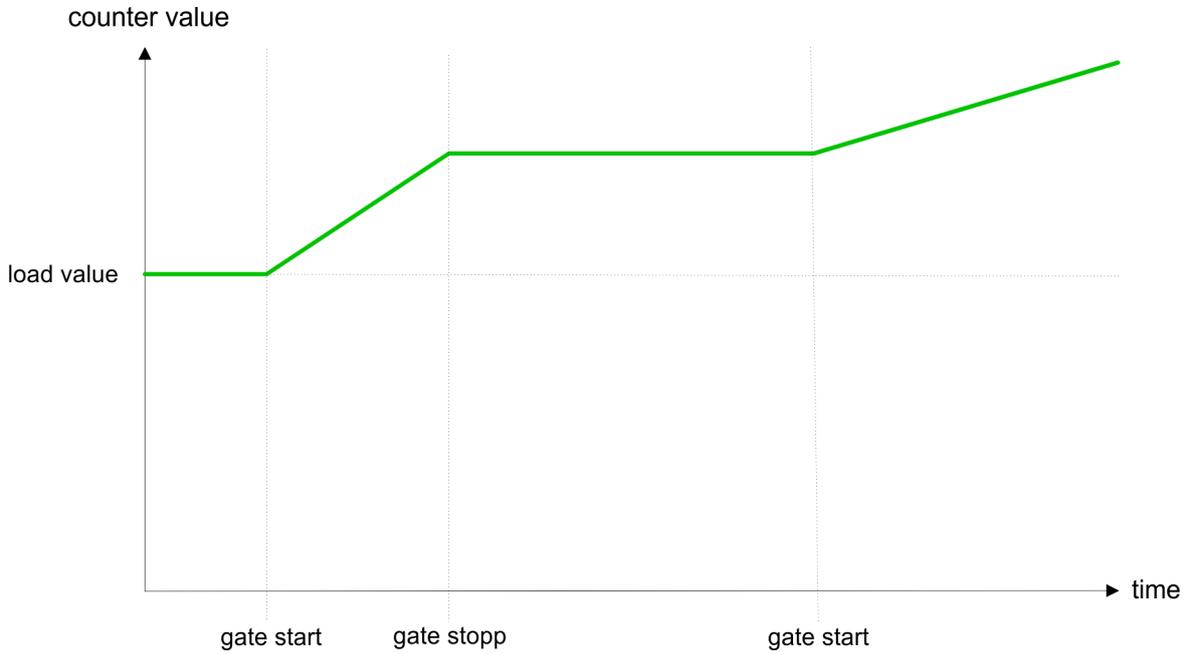
*Gate function abort and interrupt*

The parameterization defines if the gate interrupts or aborts the counter process.

- At *abort function* the counter starts counting with the *load value* after gate restart.



- At *interrupt function*, the counter starts counting with the recent *counter value* after gate restart.



## Comparison function

The *compare value* is to be pre-defined by the *output area*. The *comparison bit* may be found at the *counter status* at STS\_COMP. Please consider that the bit STS\_COMP may only be influenced when in the counter status the bit STS\_CTRL\_COMP is set. The following behavior for the *comparison bit* may be pre-defined via the parameterization:

- no comparison: *Comparison bit* is not influenced
- *Counter value*  $\geq$  *comparison value*: *Comparison bit* is set
- *Counter value*  $\leq$  *comparison value*: *Comparison bit* is set
- *Counter value* = *comparison value*: *Comparison bit* is set

*no comparison*

The *comparison bit* is not influenced.

*Comparison bit is set when counter value  $\geq$  comparison value*

The *comparison bit* remains set as long as the *counter value* is higher or equal *comparison value*.

*Comparison bit is set when counter value  $\leq$  comparison value*

The *comparison bit* remains set as long as the *counter value* is lower or equal *comparison value*.

*Comparison bit is set when counter value = comparison value*

When the counter reaches the *comparison value* the *comparison bit* is set. The *comparison bit* remains set as long as the comparison condition is met. When you've set a main counting direction the *comparison bit* is only set at reaching the *comparison value* from the main counting direction.

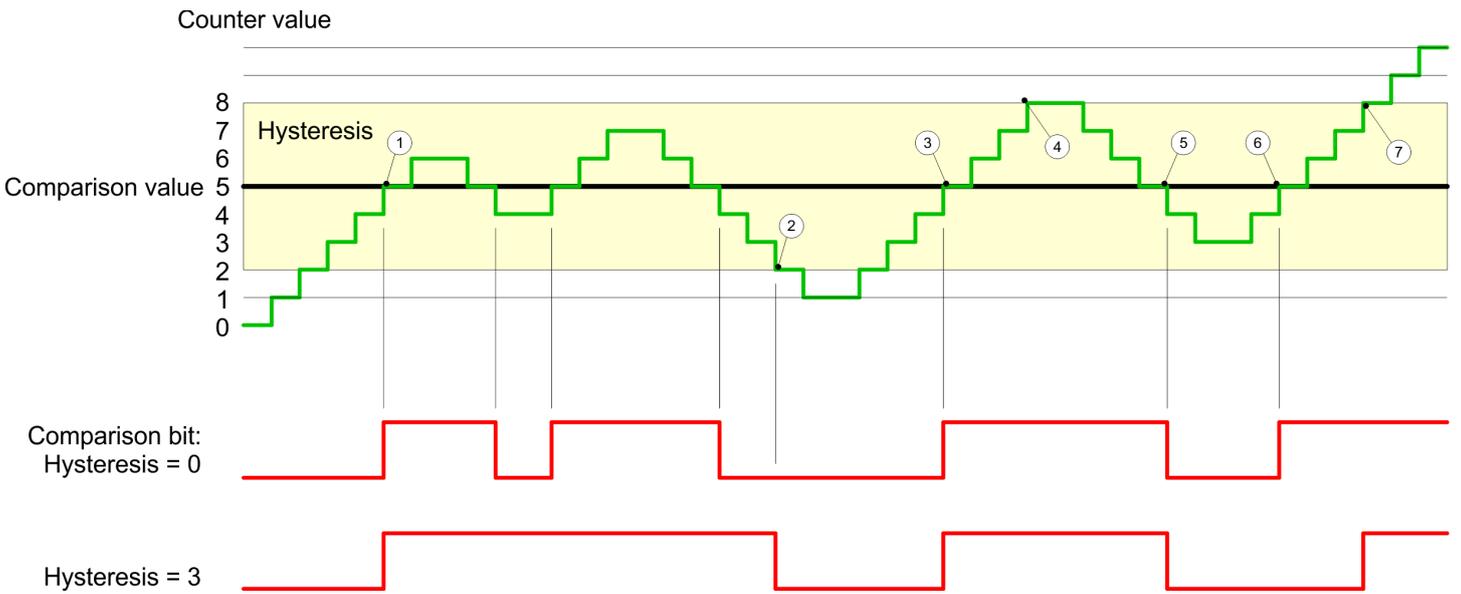


The bit STS\_COMP is set together with the bit STS\_CMP in the counter status. In contrast to the bit STS\_COMP this bit remains set as long as it is reset by setting the bit RES\_SET in the control word.

## Hysteresis

The *hysteresis* serves e.g. the avoidance of many toggle processes of the interrupt, if the counter value is in the range of the *comparison value*. You may set a range of 0 to 255. The settings 0 and 1 deactivate the hysteresis. The *hysteresis* influences the zero run, over-/underflow and *comparison value*. An activated *hysteresis* remains active after a change. The new *hysteresis* range is taken over at the next *hysteresis* event. The following pictures illustrate the behavior of the *comparison bit* for *hysteresis* 0 and *hysteresis* 3 for the according conditions:

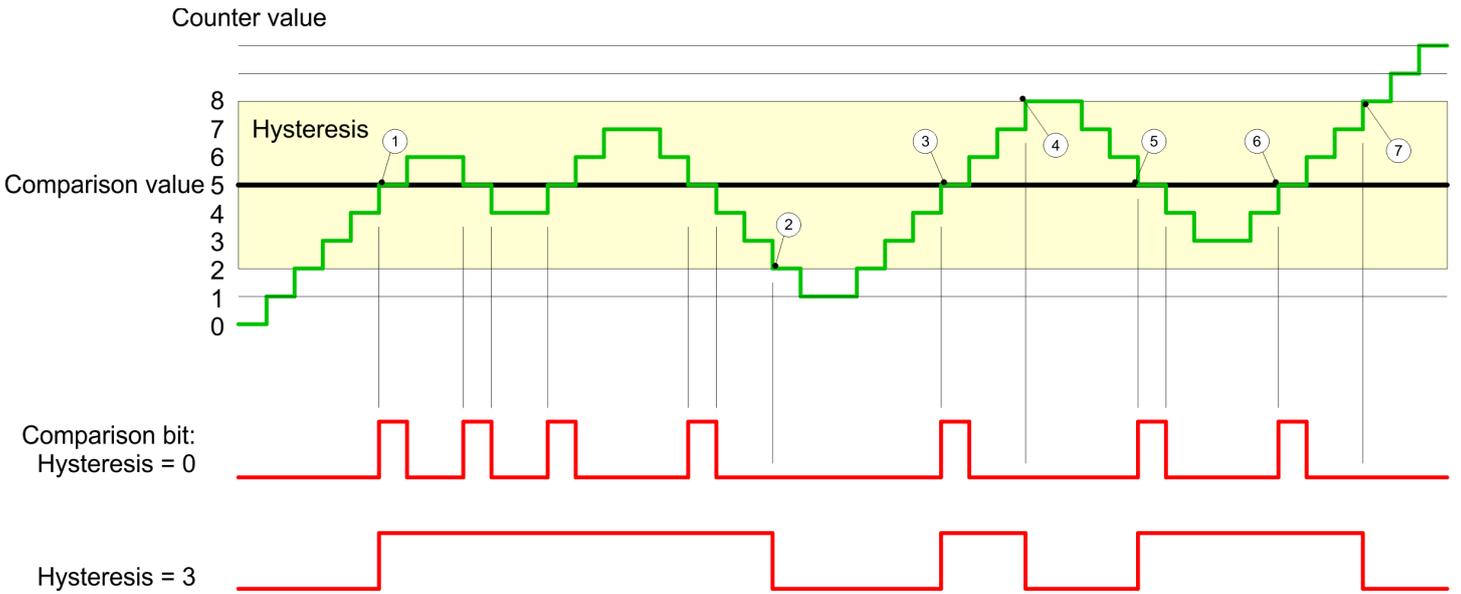
**Effect at counter value  $\geq$  comparison value**



- 1 Counter value  $\geq$  comparison value  $\rightarrow$  comparison bit is set and hysteresis activated
- 2 Leave hysteresis range  $\rightarrow$  comparison bit is reset
- 3 Counter value  $\geq$  comparison value  $\rightarrow$  comparison bit is set and hysteresis activated
- 4 Leave hysteresis range, comparison bit remains set for counter value  $\geq$  comparison value
- 5 Counter value  $<$  comparison value and hysteresis active  $\rightarrow$  comparison bit is reset
- 6 Counter value  $\geq$  comparison value  $\rightarrow$  comparison bit is not set for hysteresis active
- 7 Leave hysteresis range, comparison bit remains set for counter value  $\geq$  comparison value

With reaching the comparison condition the *hysteresis* gets active. At active *hysteresis* the comparison result remains unchanged until the *counter value* leaves the set *hysteresis* range. After leaving the *hysteresis* range a new hysteresis is only activated with again reaching the comparison conditions.

**Effect at counter value = comparison value**



- 1 Counter value = comparison value → comparison bit is set and hysteresis activated
- 2 Leave hysteresis range → comparison bit is reset and Counter value < comparison value
- 3 Counter value = comparison value → comparison bit is set and hysteresis activated
- 4 Comparison bit is reset for leaving hysteresis range and counter value > comparison value
- 5 Counter value = comparison value → comparison bit is set and hysteresis activated
- 6 Counter value = comparison value and hysteresis active → comparison bit remains set
- 7 Leave hysteresis range and counter value > comparison value → comparison bit is reset

With reaching the comparison condition the hysteresis gets active. At active hysteresis the comparison result remains unchanged until the counter value leaves the set hysteresis range. After leaving the hysteresis range a new hysteresis is only activated with again reaching the comparison conditions.

**4.6 Diagnostic and interrupt**

**Overview**

Event	Process interrupt	Diagnostics interrupt	parameterizable
Overflow	X	-	X
Underflow	X	-	X
Comparison value	X	-	X
End value	X	-	X
Diagnostics buffer overflow	-	X	-
Process interrupt lost	-	X	-

## Diagnostic and interrupt

**Hardware interrupt**

So you may react to asynchronous events, there is the possibility to activate a hardware interrupt.

- A hardware interrupt interrupts the linear program sequence and jumps depending on the master system to a corresponding Interrupt routine. Here you can react to the hardware interrupt accordingly.
- With CANopen the hardware interrupt data is transferred via an emergency telegram.
- Operating with CPU, PROFIBUS and PROFINET the hardware interrupt data were transferred via diagnostics telegram.

SX Subindex for access via EtherCAT with Index 5000h

More can be found in the according manual of your bus coupler.

Name	Bytes	Function	Default	SX
PRIT_A	1	Process interrupt	00h	02h
PRIT_B	1	State of the inputs	00h	03h
PRIT_US	2	µs ticker	00h	04h ... 05h

**PRIT\_A Process interrupt data**

Byte	Bit 7 ... 0
0	Process interrupt data <ul style="list-style-type: none"> <li>■ Bit 1 ... 0: reserved</li> <li>■ Bit 2: C0: Overflow, underflow or end value reached</li> <li>■ Bit 3: C0: Comparison value reached</li> <li>■ Bit 5 ... 4: reserved</li> <li>■ Bit 6: C1: Overflow, underflow or end value reached</li> <li>■ Bit 7: C1: Comparison value reached</li> </ul>

**PRIT\_B State of the inputs**

Byte	Bit 7 ... 0
0	State of the inputs at the moment of the process interrupt <ul style="list-style-type: none"> <li>■ Bit 0: Input value channel 0 (C0: TrackA)</li> <li>■ Bit 1: Input value channel 1 (C0: TrackB)</li> <li>■ Bit 2: Input value channel 2 (C1: TrackA)</li> <li>■ Bit 3: Input value channel 3 (C1: TrackB)</li> <li>■ Bit 7 ... 4 reserved</li> </ul>

**PRIT\_US µs ticker**

Byte	Bit 7 ... 0
0 ... 1	Value of the µs ticker at the moment of the process interrupt

**µs ticker**

In the SLIO module there is a timer (µs ticker). With PowerON the timer starts counting with 0. After  $2^{16}-1\mu\text{s}$  the timer starts with 0 again.

**Diagnostic data**

Via the parameterization you may activate a diagnostic interrupt for the module. With a diagnostic interrupt the module serves for diagnostic data for diagnostic interrupt<sub>incoming</sub>. As soon as the reason for releasing a diagnostic interrupt is no longer present, the diagnostic interrupt<sub>going</sub> automatically takes place. All events of a channel between diagnostic interrupt<sub>incoming</sub> and diagnostic interrupt<sub>going</sub> are not stored and get lost. Within this time window (1. diagnostic interrupt<sub>incoming</sub> until last diagnostic interrupt<sub>going</sub>) the MF-LED of the module is on.

DS Record set for access via CPU, PROFIBUS and PROFINET. The access happens by DS 01h. Additionally the first 4 bytes may be accessed by DS 00h.

IX Index for access via CANopen. The access happens by IX 2F01h. Additionally the first 4 bytes may be accessed by IX 2F00h.

SX Subindex for access via EtherCAT with Index 5005h.

More can be found in the according manual of your bus coupler.

Name	Bytes	Function	Default	DS	IX	SX
ERR_A	1	Diagnostic	00h	01h	2F01h	02h
MODTYP	1	Module information	18h			03h
ERR_C	1	reserved	00h			04h
ERR_D	1	Diagnostic	00h			05h
CHTYP	1	Channel type	76h			06h
NUMBIT	1	Number diagnostics bits per channel	08h			07h
NUMCH	1	Number channels of the module	02h			08h
CHERR	1	Channel error	00h			09h
CH0ERR	1	Channel specific error C0	00h			0Ah
CH1ERR	1	Channel specific error C1	00h			0Bh
CH2ERR... CH7ERR	7	reserved	00h			0Ch ... 11h
DIAG_US	4	µs ticker	00h			13h

**ERR\_A Diagnostic**

Byte	Bit 7 ... 0
0	<ul style="list-style-type: none"> <li>■ Bit 0: set at module error - error source: <ul style="list-style-type: none"> <li>– Process alarm lost (ERR_D Diagnostic, Bit 6: set)</li> <li>– Encoder power supply overload</li> </ul> </li> <li>■ Bit 1: set at internal error - error source: <ul style="list-style-type: none"> <li>– Process alarm lost (ERR_D Diagnostic, Bit 6: set)</li> </ul> </li> <li>■ Bit 2: set at external error - error source: <ul style="list-style-type: none"> <li>– Encoder power supply overload</li> </ul> </li> <li>■ Bit 3: set at channel error - error source: <ul style="list-style-type: none"> <li>– Process alarm lost (ERR_D Diagnostic, Bit 6 set)</li> </ul> </li> <li>■ Bit 7 ... 4: reserved</li> </ul>

## Diagnostic and interrupt

## MODTYP Modul information

Byte	Bit 7 ... 0
0	<ul style="list-style-type: none"> <li>■ Bit 3 ... 0: Module class               <ul style="list-style-type: none"> <li>– 1000b: Function module</li> </ul> </li> <li>■ Bit 4: set at channel information present</li> <li>■ Bit 7 ... 5: reserved</li> </ul>

## ERR\_C reserved

Byte	Bit 7 ... 0
0	reserved

## ERR\_D Diagnostic

Byte	Bit 7 ... 0
0	<ul style="list-style-type: none"> <li>■ Bit 2 ... 0: reserved</li> <li>■ Bit 3: set at internal diagnostics buffer overflow - error source:               <ul style="list-style-type: none"> <li>– More than 16 diagnostic alarms are pending.</li> </ul> </li> <li>■ Bit 5 ... 4: reserved</li> <li>■ Bit 6: Process interrupt lost - error source:               <ul style="list-style-type: none"> <li>– A process alarm is pending and another process alarm has occurred on the same channel. The diagnostic buffer can only hold one process alarm per channel.</li> </ul> </li> <li>■ Bit 7: reserved</li> </ul>

## CHTYP Channel type

Byte	Bit 7 ... 0
0	<ul style="list-style-type: none"> <li>■ Bit 6 ... 0: Channel type               <ul style="list-style-type: none"> <li>– 76h: Counter module</li> </ul> </li> <li>■ Bit 7: reserved</li> </ul>

## NUMBIT Diagnostic bits

Byte	Bit 7 ... 0
0	Number of diagnostics bits of the module per channel (here 08h)

## NUMCH Channels

Byte	Bit 7 ... 0
0	Number of channels of the module (here 02h)

## CHERR Channel error

Byte	Bit 7 ... 0
0	<ul style="list-style-type: none"> <li>■ Bit 0: set at error in channel group 0</li> <li>■ Bit 1: set at error in channel group 1</li> <li>■ Bit 7 ... 2: reserved</li> </ul>

**CH0ERR ... CH1ERR**  
 channel specific

Byte	Bit 7 ... 0
0	Diagnostic interrupt due to process interrupt lost at ... <ul style="list-style-type: none"> <li>■ Bit 1 ... 0: reserved</li> <li>■ Bit 2: Overflow/underflow/end value</li> <li>■ Bit 3: Comparison value reached</li> <li>■ Bit 7 ... 4: reserved</li> </ul>

**CH2ERR ... CH7ERR**  
 reserved

Byte	Bit 7 ... 0
0	reserved

**DIAG\_US**  $\mu$ s ticker

Byte	Bit 7 ... 0
0 ... 3	Value of the $\mu$ s ticker at the moment of the diagnostic

 *$\mu$ s ticker*

In the SLIO module there is a timer ( $\mu$ s ticker). With PowerON the timer starts counting with 0. After  $2^{32}-1\mu$ s the timer starts with 0 again.